Technical data sheet

AHX120-3-300

Customizable Non Fail-Safe actuator for controlling dampers in typical commercial HVAC applications.

- Actuating force motor 450 N [100 lbf]
- Nominal voltage AC 100...240 V
- Control On/Off, Floating point







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Electrical data	Nominal voltage	AC 100240 V		
	Nominal voltage frequency	50/60 Hz		
	Nominal voltage range	AC 85265 V		
	Power consumption in operation	2.5 W		
	Power consumption in rest position	0.5 W		
	Transformer sizing	4.5 VA		
	Electrical Connection	18 GA appliance cables, 1 m, 3 m or 5 m, with 1/2" conduit connector		
	Overload Protection	electronic throughout full stroke		
Functional data	Actuating force motor	450 N [100 lbf]		
	Direction of motion motor	reversible with switch		
	Manual override	external push button		
	Stroke	12" [300 mm]		
	Running Time (Motor)	150 s / 100 mm		
	Noise level, motor	35 dB(A)		
Safety data	Power source UL	Class 2 Supply		
	Degree of protection IEC/EN	IP54		
	Degree of protection NEMA/UL	NEMA 2		
	Enclosure	UL Enclosure Type 2		
	Agency Listing	cULus acc. to UL60730-1A/-2-14, CAN/CSA E60730-1:02		
		CE acc. to 2014/30/EU and 2014/35/EU		
	Quality Standard	ISO 9001		
	UL 2043 Compliant	Suitable for use in air plenums per Section 300.22(C) of the NEC and Section 602 of the IMC		
	Ambient humidity	Max. 95% RH, non-condensing		
	Ambient temperature	-22122°F [-3050°C]		
	Storage temperature	-40176°F [-4080°C]		
	Servicing	maintenance-free		
Weight	Weight	2.9 lb [1.3 kg]		
Materials	Housing material	UL94-5VA		

Footnotes †Rated Impulse Voltage 800V, Type of Action 1, Control Pollution Degree 2.

Product features

Application For on/off and floating point control of dampers in HVAC systems. Actuator sizing should be

done in accordance with the damper manufacturer's specifications.

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Operation

The actuator is not provided with and does not require any limit switches, but is electronically protected against overload. The anti-rotation strap supplied with the actuator will prevent lateral movement.

The AHX... series provides 4, 8, or 12 inches of linear stroke. The stroke of the gear rack can be adjusted on both sides in increments of 0.8 in [20 mm] by means of the mechanical end stops.

When reaching the damper or actuator end position, the actuator automatically stops.

The gears can be manually disengaged with a button on the actuator cover.

The AHX120-3... actuators use a sensorless brushless DC motor, which is controlled by an Application Specific Integrated Circuit (ASIC). The ASIC monitors and controls the actuator's rotation and provides a digital rotation sensing (DRS) function to prevent damage to the actuator in a stall condition. Power consumption is reduced in holding mode.

Typical specification

Floating point, on/off control damper actuators shall be electronic type, with integrated linear stroking arm. Actuators shall have brushless DC motor technology and be protected from overload at all positions of linear stroke. Actuators shall have reversing switch and manual override on the cover. Run time shall be constant and independent of torque. Actuators shall be cUL listed, have a 5-year warranty, and be manufactured under ISO 9001 International Quality Control Standards. Actuators shall be as manufactured by Belimo.

Accessories

Electrical accessories	Description	Туре	
	Cable conduit connector 1/2"	TF-CC US	
Mechanical accessories	Description	Туре	
	Ball joint suitable for damper crank arm KH8 / KH10, Multipack 10 pcs.	KG10A	
	Ball joint suitable for damper crank arm KH8, Multipack 10 pcs.	KG6	
	Ball joint suitable for damper crank arm KH8, Multipack 10 pcs.	KG8	
	Push rod for KG6 & KG8 ball joints (36" L, 5/16" diameter).	SH8	
	Rotary support, for linear actuator, for compensation of transverse forces	Z-DS1	
	3/8"-16 shaft clevis for AHK/AH.	Z-KSC	
	Bracket for AHK/AH/I H linear actuators.	7G-119	

Electrical installation

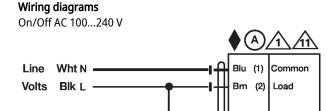
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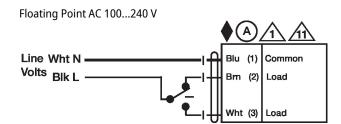
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A) Actuators with appliance cables are numbered.

Provide overload protection and disconnect as required.

 $\overline{\lambda}$ Actuators may be connected in parallel if not mechanically linked. Power consumption and input impedance must be observed.







Dimensions

