

EFB24-SR-S - Damper Actuator

Modulating, Spring Return, 24 VAC/DC, for 2 to 10 VDC or 4 to 20 mA Control Signal



Technical Data	
Power Supply	24 VAC±20%, 50/60Hz, 24 VDC+20%/-10%
Power Consumption Running	8 W
Power Consumption Holding	4.5 W
Transformer Sizing	14 VA (class 2 power source)
Shaft Diameter	1/2" to 1.05" round, centers on 3/4" with insert, 1.05" without insert
Electrical Connection	(2) 3 ft [1 m], 18 GA appliance cables with 1/2" conduit connectors
Overload Protection	electronic throughout 0° to 95° rotation
Electrical Protection	actuators are double insulated
Operating Range Y	2 to 10 VDC, 4 to 20 mA w/ ZG-R01 (500 Ω, 1/4 W resistor)
Input Impedance	100 k Ω for 2 to 10 VDC (0.1 mA), 500 Ω for 4 to 20 mA
Feedback Output U	2 to 10 VDC, 0.5 mA max
Angle of Rotation	max. 95° (adjustable with mechanical end stop, 35° to 95°)
Torque	270 in-lbs [30 Nm] minimum
Direction of Rotation (Motor)	reversible with built-in switch
Direction of Rotation (Fail-Safe)	reversible with CW/CCW mounting
Position Indication	visual indicator, 0° to 95° (0° is full spring return position)
Manual Override	5 mm hex crank (3/16" Allen), supplied
Running Time (Motor)	95 sec
Running Time (Fail-Safe)	<20 sec @ -4°F to 122°F [-20°C to 50°C], <60 sec @ -22°F [-30°C]
Humidity	max. 95% RH non-condensing
Ambient Temperature Range	-22°F to +122°F [-30°C to +50°C]
Storage Temperature Range	-40°F to +176°F [-40°C to +80°C]
Housing	NEMA 2, IP54, UL enclosure type 2
Housing Material	Aluminum die cast and plastic casing
Agency Listings†	cULus acc. to UL60730-1A/-2-14, CAN/CSA E60730-1:02, CE acc. to 2004/108/EC and 2006/95/EC
Noise Level (Motor)	≤56.5 dB (A)
Noise Level (Fail-Safe)	≤71 dB (A)
Servicing	maintenance free
Quality Standard	ISO 9001
Weight	10.14 lb [4.6 kg]
Auxiliary Switch	2 x SPDT, 3A resistive (0.5A inductive) @ 250 VAC, one set at +10°, one adjustable 10° to 85°

†Rated Impulse Voltage 800V, Type of Action 1.AA.B, Control Pollution Degree 3.

Torque min. 270 in-lb, for control of air dampers

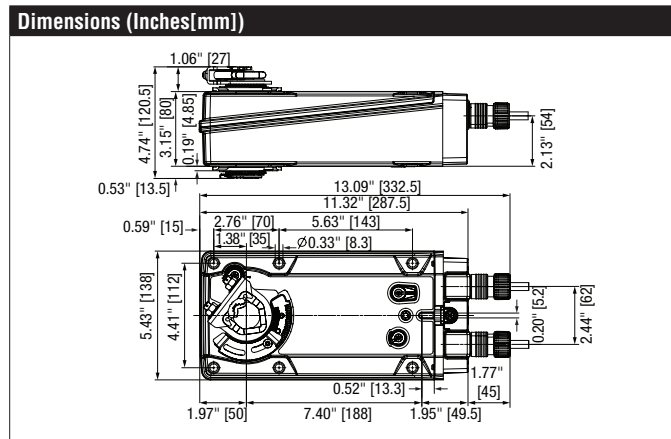
Application

For fail-safe, modulating control of dampers in HVAC systems. Actuator sizing should be done in accordance with the damper manufacturer's specifications. The actuator is mounted directly to a damper shaft up to 1.05" in diameter by means of its universal clamp. A crank arm and several mounting brackets are available for applications where the actuator cannot be direct coupled to the damper shaft. The actuator operates in response to a 2 to 10 VDC or, with the addition of a 500Ω resistor, a 4 to 20 mA control input from an electronic controller or positioner. A 2 to 10 VDC feedback signal is provided for position indication. Not to be used for a master-slave application.

Operation

The EF.24-SR-S series actuators provide true spring return operation for reliable failsafe application and positive close off on air tight dampers. The spring return system provides constant torque to the damper with, and without, power applied to the actuator. The EF.24-SR-S series provides 95° of rotation and is provided with a graduated position indicator showing 0° to 95°. The EF.24-SR-S uses a brushless DC motor which is controlled by an Application Specific Integrated Circuit (ASIC) and a microprocessor. The microprocessor provides the intelligence to the ASIC to provide a constant rotation rate and to know the actuator's exact fail-safe position. The ASIC monitors and controls the brushless DC motor's rotation and provides a digital rotation sensing function to prevent damage to the actuator in a stall condition. The actuator may be stalled anywhere in its normal rotation without the need of mechanical end switches. The EF.24-SR-S versions are provided with two built-in auxiliary switches. These SPDT switches provide safety interfacing or signaling, for example, for fan start-up. The switching function at the fail-safe position is fixed at +10°, the other switch function is adjustable between +10° to +85°. The EF.24-SR-S actuator is shipped at +5° (5° from full fail-safe) to provide automatic compression against damper gaskets for tight shut-off.

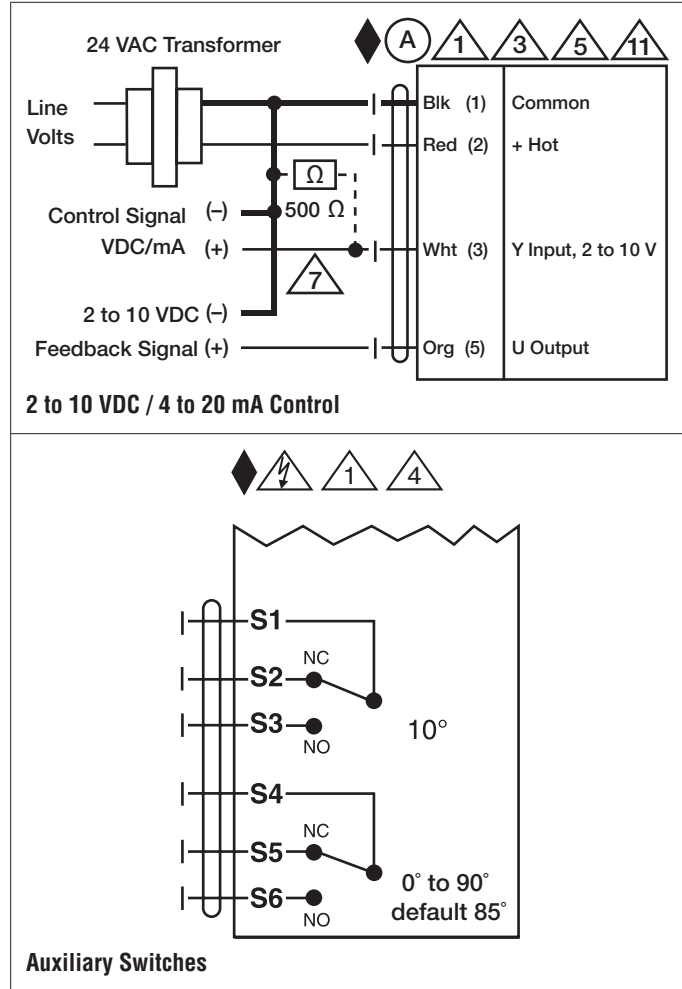
Installation Note: Use flexible metal conduit. Push the UL listed conduit fitting device over the actuator's cable to butt against the enclosure. Screw in conduit connector. Jacket the actuator's input wiring with UL listed flexible conduit. Properly terminate the conduit in a suitable junction box.



Accessories	
AV8-25	9.8" shaft extension for 5/16" to 1" diameter shafts.
EF-P	Anti-rotation bracket EFB(X)/GKB(X)/GMB(X).
IND-EFB	EFB(X) position indicator.
K9-2	Standard EFB(X) clamp (1/2" to 1.05").
KG10A	Ball joint for 3/8" diameter rod, zinc plated.
KH10	Univ. crankarm, slot 21/64" w, for 9/16" to 1" dia. shafts.
KH-EFB	EFB(X) crankarm (with 1.05" diameter shaft pass through).
SH10	Push rod for KG10A ball joint (36" L, 3/8" diameter).
TOOL-07	13 mm wrench.
ZG-100	Univ. right angle bracket (17" H x 11-1/8" W x 6" base).
ZG-120	Jackshaft mounting bracket.
ZG-DC1	Damper clip for damper blade, 3.5" width.
ZG-DC2	Damper clip for damper blade, 6" width.
ZG-EFB	EFB(X) crankarm adaptor kit.
ZG-JSA-3	1.05" diameter jackshaft adaptor (12" L).
ADS-100	Analog to digital switch for modulating actuators.
IRM-100	Input rescaling module for modulating actuators.
PS-100	Actuator power supply and control simulator.
PTA-250	Pulse width modulation interface for modulating actuators.
SGA24	Positioner control for modulating actuators (surface mount).
SGF24	Positioner control for modulating actuators (flush mount).
TF-CC US	Cable conduit connector, 1/2".
ZG-R01	4 to 20 mA adaptor, 500Ω, 1/4 W resistor w 6" pigtail wires.
ZG-R02	50% voltage divider kit (resistors with wires).
ZG-SGF	Mounting plate for SGF.
ZG-X40	120 to 24 VAC, 40 VA transformer.

Typical Specification

Spring return control damper actuators shall be direct coupled type which require no crank arm and linkage and be capable of direct mounting to a jackshaft up to a 1.05" diameter. The actuator must provide modulating damper control in response to a 2 to 10 VDC or, with the addition of a 500Ω resistor, a 4 to 20 mA control input from an electronic controller or positioner. The actuators must be designed so that they may be used for either clockwise or counter clockwise fail-safe operation. Actuators shall use a brushless DC motor controlled by a microprocessor and be protected from overload at all angles of rotation. Run time shall be constant, and independent of torque. A 2 to 10 VDC feedback signal shall be provided for position feedback. Actuators with auxiliary switches must be constructed to meet the requirements for Double Insulation so an electrical ground is not required to meet agency listings. Actuators shall be cULus listed and have a 5 year warranty, and be manufactured under ISO 9001 International Quality Control Standards. Actuators shall be as manufactured by Belimo.



EFB24-SR-S - Damper Actuator

Modulating, Spring Return, 24 VAC/DC, for 2 to 10 VDC or 4 to 20 mA Control Signal

Wiring Diagrams



WARNING! LIVE ELECTRICAL COMPONENTS!

During installation, testing, servicing and troubleshooting of this product, it may be necessary to work with live electrical components. Have a qualified licensed electrician or other individual who has been properly trained in handling live electrical components perform these tasks. Failure to follow all electrical safety precautions when exposed to live electrical components could result in death or serious injury.



Meets cULus requirements without the need of an electrical ground connection.



Apply only AC line voltage or only UL-Class 2 voltage to the terminals of auxiliary switches. Mixed or combined operation of line voltage/safety extra low voltage is not allowed.



Actuators with appliance cables are numbered.



Provide overload protection and disconnect as required.



Actuators may also be powered by 24 VDC.



Two built-in auxiliary switches (2x SPDT), for end position indication, interlock control, fan startup, etc.



Only connect common to negative (-) leg of control circuits.



A 500 Ω resistor (ZG-R01) converts the 4 to 20 mA control signal to 2 to 10 VDC.



Actuators may be connected in parallel if not mechanically linked. Power consumption and input impedance must be observed.