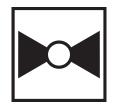






2-year warranty



Technical data

Fu	ınd	tio	nal	da	ata

Valve Size	14" [350]		
Fluid	chilled or hot water, up to 60% glycol		
Fluid Temp Range (water)	-22250°F [-30120°C]		
Body Pressure Rating	ANSI Class Consistent with 125, 232 psi CWP		
Close-off pressure Δps	150 psi		
Servicing	maintenance-free		
Rangeability Sv	10:1 (for 3070° range)		
Flow Pattern	2-way		
Leakage rate	0%		
Controllable flow range	90° rotation		
Cv	11917		
ANSI Class	Consistent with 125		
Body pressure rating note	232 psi CWP		
Maximum Velocity	12 FPS		
Lug threads	1-8 UNC		
Valve body	Ductile cast iron ASTM A536		
Body finish epoxy powder coating (blue RAL 5002)			

Materials

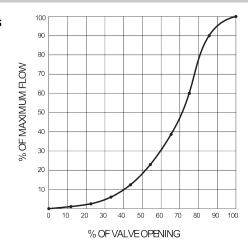
Valve body Ductile cast iron ASTM A536	
Body finish	epoxy powder coating (blue RAL 5002)
Stem seal	EPDM (lubricated)
Seat	EPDM
End fitting	for use with ANSI class 125/150 flanges
Bearing	RPTFE
Disc	304 stainless steel
Gear operator materials	Gears - hardened steel
Non-Spring	SY5

Suitable actuators



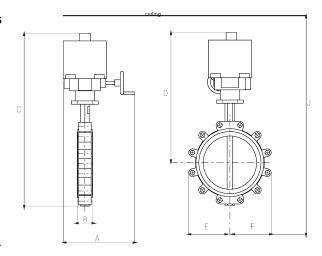
Product features

Flow/Mounting details



Dimensions

Dimensional drawings



SY5..

Α	В	C	D	E	F	J	Number of Bolt Holes
11.5" [293]	3.2" [82]	37.6" [955]	27.2" [691]	10.2" [260]	10.2" [260]	45.7" [1161]	12



Technical data

Technical data sheet

SY5-24MFT

NEMA 4X, Modulating Control, Non-Spring Return, 24 V, for DC 2...10 V or 4...20 mA

Electrical data

Nominal voltage

Noise level, motor

Position indication





	Nominal voltage frequency	50/60 Hz
	Transformer sizing	214 VA
	Current consumption	8.9 A
	Auxiliary switch	2 x SPDT, 3 A resistive (0.5 A inductive) @ AC 250 V, one set at 10°, one set at 85°
	Switching capacity auxiliary switch	3 A resistive (0.5 A inductive) @ AC 250 V
	Electrical Connection	Terminal blocks
	Overload Protection	thermally protected 135°C cut-out
	Internal Humidty Control	resistive heating element
Functional data	Operating range Y	210 V
	Input Impedance	100 kΩ
	Position feedback U	210 V
	Position Feedback	210 V
	Direction of motion motor	selectable with switch 0/1
	Manual override	hand wheel
	Angle of rotation	90°
	Running Time (Motor)	26 s
	Duty cycle value	75%

Degree of protection IEC/EN	IP66/67
Degree of protection NEMA/UL	NEMA 4X
Enclosure	UL Enclosure Type 4X
Agency Listing	ISO, CE, cCSAus
Quality Standard	ISO 9001
Ambient temperature	-22150°F [-3065°C]
Storage temperature	-40176°F [-4080°C]
Ambient humidity	max. 95% r.H., non-condensing
Servicing	maintenance-free
Weight	49 lb [22 kg]
Housing material	die cast aluminium
Gear train	high alloy steel gear sets, self locking

45 dB(A)

top mounted domed indicator

AC/DC 24 V

Product features

Application

Weight

Materials

Safety data

SY Series actuators are fractional horsepower devices, and utilize full-wave power supplies. Observe wire sizing and transformer sizing requirements. Proportional models CANNOT be connected to Belimo direct coupled (AF, AM, GM...etc) actuator power supplies or any type of half-wave device. You MUST use a



separate, dedicated transformer or power supply to power the SY actuator. Please do not connect other automation equipment to the dedicated SY supply source. You MUST use four wires (plus a ground) to control a proportional control SY actuator (See SY Wiring Section).

Accessories

Gateways	Description	Туре
	Gateway MP to BACnet MS/TP	UK24BAC
	Gateway MP to LonWorks	UK24LON
	Gateway MP to Modbus RTU	UK24MOD
Service tools	Description	Туре
	Connection cable 10 ft [3 m], A: RJ11 6/4 ZTH EU, B: 3-pin Weidmüller and supply connection	ZK4-GEN
	Service Tool, with ZIP-USB function, for parametrisable and communicative Belimo actuators, VAV controller and HVAC performance devices	ZTH US

Electrical installation



> INSTALLATION NOTES

6 Do not change sensitivity or dip switch setting with power applied.

61 Power supply Common/Neutral and Control Signal "-"wiring to a common is prohibited. Terminals 4 and 6 need to be wired separately.

kisolation relays must be used in parallel connection of multiple actuators using a common control signal inputs. The relays should be DPDT.

isolation relays are required in parallel applications. The reason parallel applications need isolation relays is that the motor uses two sets of windings, one for each direction. When one is energized to turn the actuator in a specific direction a voltage is generated in the other due to the magnetic field created from the first. It's called back EMF. This is not an issue with one actuator because the voltage generated in the second winding isn't connected to anything so there is no flow. On parallel applications without isolation, this EMF voltage energizes the winding it is connected to on the other actuators in the system, the actuators are tying to turn in both directions at once. The EMF voltage is always less than the supply voltage due to the resistance of the windings, so while the actuator still turns in the commanded direction, the drag from the other reduces the torque output and causes overheating.



Warning! Live Electrical Components!

During installation, testing, servicing and troubleshooting of this product, it may be necessary to work with live electrical components. Have a qualified licensed electrician or other individual who has been properly trained in handling live electrical components perform these tasks. Failure to follow all electrical safety precautions when exposed to live electrical components could result in death or serious injury.

