

F7150HD, 3-Way Butterfly Valve

Resilient Seat, 304 Stainless Steel Disc



Technical Data

Service	chilled, hot water, up to 60% glycol
Flow Characteristic	modified linear
Controllable Flow Range	90° rotation
Size [mm]	6" [150]
End Fitting	for use with ANSI Class 125/150 flanges
Body	ductile iron ASTM A536
Body Finish	Epoxy powder coated
Ball Seat	EPDM standard
Shaft	416 stainless steel
Bushings	RPTFE
Disc	304 stainless steel
Body Pressure Rating [psi]	200 psi at -20°F to +150°F
Number of Bolt Holes	8
Lug Threads	3/4-10 UNC
Media Temperature Range (Water)	-22°F to 250°F [-30°C to 120°C]
Close-Off Pressure	200 psi
Rangeability	10:1 (for 30° to 70° range)
Maximum Velocity	12 FPS
Cv	1579
Weight	137.3 lb [62.3 kg]
Leakage	0%
Servicing	maintenance free

Product Features

200 psi (2" to 12") and 150 psi (14" to 24") Bubble tight shut-off, Long stem design allows for 2" insulation, Valve face-to-face dimensions comply with API 609 & MSS-SP-67, Completely assembled and tested, Ready for installation, Tees comply with ASM/ANSI B.

Application

These valves are designed to meet the needs of HVAC and commercial applications requiring 0% leakage for liquids. Typical applications include chiller isolation, cooling tower isolation, change-over systems, large air handler coil control, bypass and process control applications. The large Cv values provide for an economical control valve solution for larger flow applications. Designed for use in ANSI flanged piping systems.

Jobsite Note

Valves should be stored in a weather protected area prior to construction. Complete installation recommendations can be found in Belimo's Installation and Maintenance Instructions for F6/F7... Butterfly Valves.

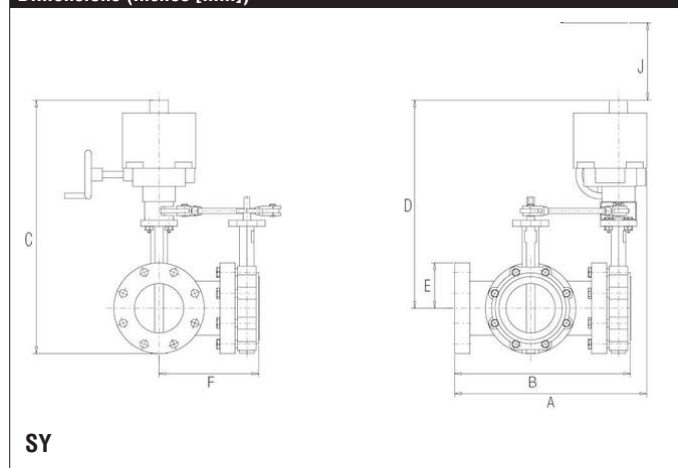
Flow/Cv

Cv 10°	Cv 20°	Cv 30°	Cv 40°	Cv 50°	Cv 60°	Cv 70°	Cv 80°	Cv 90°
0.8	45	95	205	366	605	958	1437	1579

Suitable Actuators

	Non-Spring
F7150HD	SY4

Dimensions (Inches [mm])



A	B	C	D	E	F	J
19.7" [499]	18.25" [463]	28.74" [730]	23.4" [594]	5.5" [140]	10.25" [260]	8.8" [225]

SY4-110

On/Off Floating Point, Non-Spring Return, 110 V



Application

SY Series actuators are fractional horsepower devices, and utilize full-wave power supplies. Observe wire sizing and transformer sizing requirements. Proportional models CANNOT be connected to Belimo direct coupled (AF, AM, GM...etc) actuator power supplies or any type of half-wave device. You MUST use a separate, dedicated transformer or power supply to power the SY actuator. Please do not connect other automation equipment to the dedicated SY supply source. You MUST use four wires (plus a ground) to control a proportional control SY actuator (See SY Wiring Section).

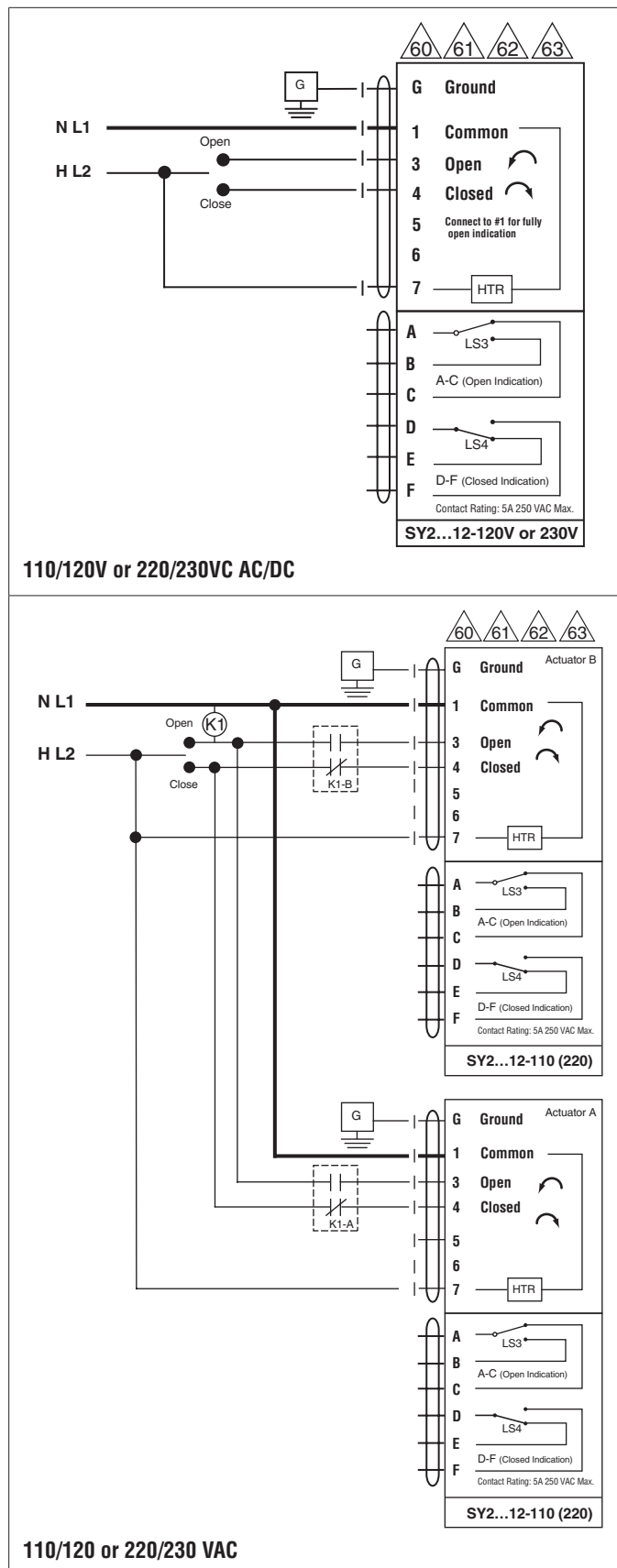
Technical Data	
Power Supply	120 VAC \pm 10%, 50/60 Hz
Power Consumption Running	196 W
Transformer Sizing	216 (class 2 power source)
Electrical Connection	terminal block
Overload Protection	thermally protected 135°C cut-out
Operating Range Y	on/off, floating point
Input Impedance	1000 Ω
Angle of Rotation	90°
Torque	3560 in-lbs [400 Nm] minimum
Duty cycle	30 %
Direction of Rotation (Motor)	reversible with built-in switch
Position Indication	top mounted domed indicator
Manual Override	hand wheel
Running Time (Motor)	18 sec
Internal Humidity Control	resistive heating element
Humidity	5 to 100% RH (UL Type 4)
Ambient Temperature Range	-22°F to 150°F [-30°C to 65°C]
Storage Temperature Range	-40°F to 176°F [-40°C to 80°C]
Housing	NEMA 4X, IP66/67, UL enclosure type 4
Housing Material	die cast aluminum alloy
Gear Train	high alloy steel gear sets, self locking
Agency Listings	ISO, CE, cCSAus
Noise Level (Motor)	<45 dB (A)
Servicing	maintenance free
Quality Standard	ISO 9001
Weight	49.6 lb [22.5 kg]
Auxiliary Switch	2 x SPDT 3A resistive (0.5A inductive) @ 250 VAC, one set at +10° and one set at 85°

Wiring Diagrams
INSTALLATION NOTES

- Do not change sensitivity or dip switch setting with power applied.
- Power supply Common/Neutral and Control Signal “-” wiring to a common is prohibited. Terminals 4 and 6 need to be wired separately.
- Isolation relays must be used in parallel connection of multiple actuators using a common control signal inputs. The relays should be DPDT.
- Isolation relays are required in parallel applications. The reason parallel applications need isolation relays is that the motor uses two sets of windings, one for each direction. When one is energized to turn the actuator in a specific direction a voltage is generated in the other due to the magnetic field created from the first. It's called back EMF. This is not an issue with one actuator because the voltage generated in the second winding isn't connected to anything so there is no flow. On parallel applications without isolation, this EMF voltage energizes the winding it is connected to on the other actuators in the system, the actuators are trying to turn in both directions at once. The EMF voltage is always less than the supply voltage due to the resistance of the windings, so while the actuator still turns in the commanded direction, the drag from the other reduces the torque output and causes overheating.

WARNING! LIVE ELECTRICAL COMPONENTS!

During installation, testing, servicing and troubleshooting of this product, it may be necessary to work with live electrical components. Have a qualified licensed electrician or other individual who has been properly trained in handling live electrical components perform these tasks. Failure to follow all electrical safety precautions when exposed to live electrical components could result in death or serious injury.



SY4-110

On/Off Floating Point, Non-Spring Return, 110 V

