

Please read this manual before proceeding to install this controller or any other Onyxx LX device.

This manual applies to <u>Onyx LX Ulsoftware version 4.0</u> and higher and using <u>firmware version 1.050</u> and higher.

All firmware updates must be done utilizing a Supplied USB-COM adapter or USB to MSTP converter cable.

Installations shall be made by a properly certified technician and respect all local mandatory codes and regulations.

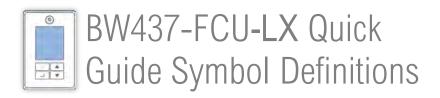
Electronic controls are static sensitive devices: discharge yourself properly before manipulating and installing a controller.

Any short circuit or incorrect wiring may permanently damage the controller or the controlled equipment.

Double check all wiring before applying power.

If a control failure could lead to personal injury and/or loss of property, it becomes the responsibility of the installer to add safety devices and/or alarm system to protect against failures.





The following table lists the symbols used in this document to denote certain conditions:

Symbol	Definition
	ATTENTION: Identifies information that requires special consideration
	TIP: Identifies advice or hints for the user, often in terms of performing a task
日	REFERENCE _ INTERNAL: Identifies an additional source of information within the bookset.
CAUTION	Indicates a situation which, if not avoided, may result in equipment or work (data) on the system being damaged or lost, or may result in the inability to properly operate the process.
1	Indicates a situation where users must observe precautions for handling electrostatic sensitive devices.
<u> </u>	CAUTION: Indicates a potentially hazardous situation which, if not avoided, may result in minor or moderate injury. It may also be used to alert against unsafe practices.
	WARNING: Indicates a potentially hazardous situation which, if not avoided, could result in serious injury or death.



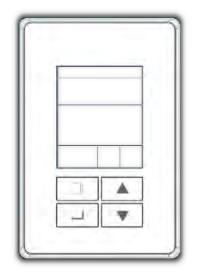


	ymbol's definition	
D	escription and model numbers	
lr	stallation	
	Mounting	
	Internal Jumper Settings	
	Power Supply Connections	
	I/O's Wiring Instructions	
lr	terface	
	Buttons	
	Local LCD display	
U	sing the menus	
	Network configuration settings	
	Quick setup menu	
A	pplications, sequences and curves	
	Temperature control (Main PID loops)	
	4 Pipes modulating 0-10 Vdc valves	
	4 Pipes modulating floating valves	
	4 Pipes on/off N.C. valves.	
	4 Pipes on/off N.O. valves.	
	2 Pipes modulating 0-10 Vdc valves	
	2 Pipes modulating floating valves	
	2 Pipes on/off N.C. valves	
	2 Pipes on/off N.O. valves	
	Single speed analog fan control	
	3 speeds fan control	
	2 speeds fan control	
	Single speed on/off fan control	
_	Reheat control	
	ervice menu	
	est IO menu	
	bject list	
	hysical Inputs and Outputs	
	nalog Values	
	inary Values	
	lultiStates Values	
	S-485 Network Guidelines.	
S	pecifications	

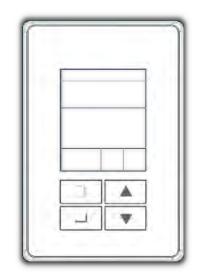




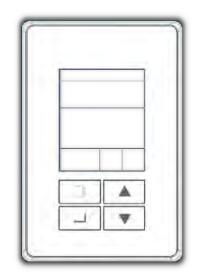
BW437-FCU-LX Quick Guide Models Available



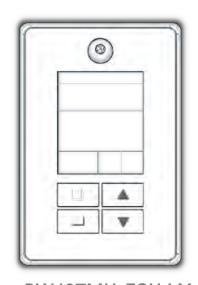
BW437-FCU-LX
Base Model



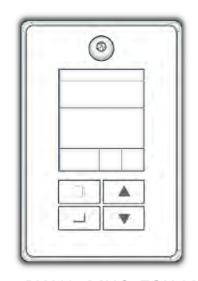
BW437H-FCU-LX
Base Model Base
Model w/Humidity
Sensor



BW437HC-FCU-LX
Base Model
w/Humidity Sensor
w/C02 Sensor



BW437MH-FCU-LX
Base Model
w/PIR Motion Sensor
w/Humidity Sensor



BW437MHC-FCU-LX
Base Model
w/PIR Motion Sensor
w/Humidity Sensor
w/C02 Sensor

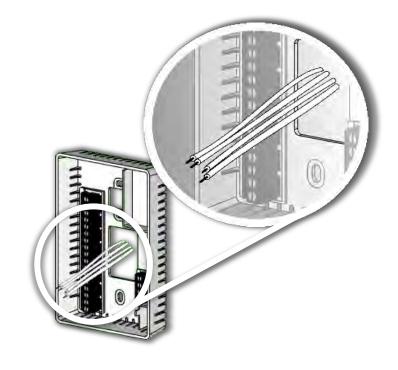


Installation BW437-FCU-LX Mounting Instructions

- 1. After unpacking your BW437-FCU-LX, unscrew the retaining screw at the bottom of the unit.
- 2. Gently pull the cover away from the base.



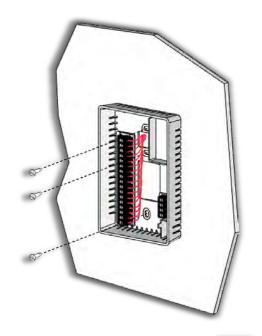
3. Pull the wires through the hole in the base.



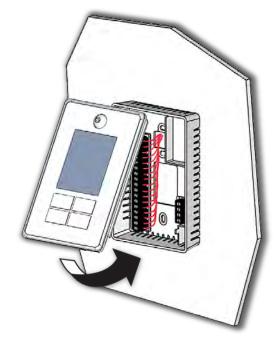


Installation BW437-FCU-LX Mounting Instructions

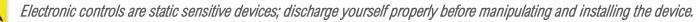
4. Connect the wires to the terminal, referring to the chart inside the base for the proper connections.



5. Before replacing the cover, make sure that you have made any necessary modification to DIP switch or jumper settings (see "Jumper Settings").





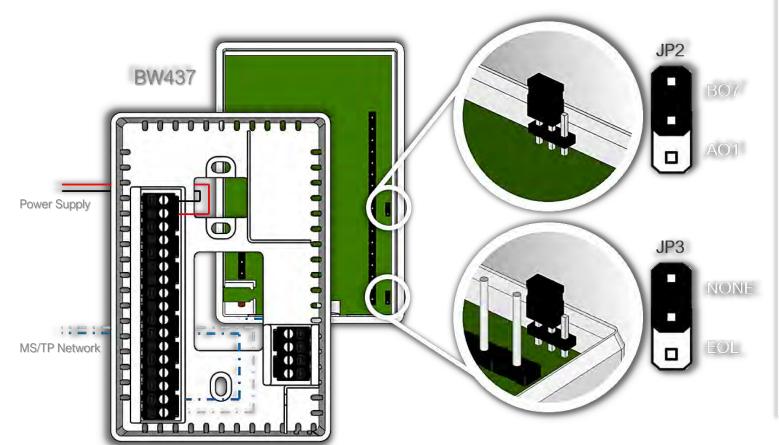




Short circuits or incorrect wiring may permanently damage the controller. Double check your wiring before applying power. If a control failure could lead to personal injury and/or loss of property, the installer must add safety devices and/or alarm systems to protect against failures.



Installation Internal Jumper Settings



Jumpers setting:

JP2 to select between BO7 or AO1: Jumper up = Using BO7 (Low Speed Fan) Jumper down = Using AO1 (ECM)

JP3 enables EOL (120 Ohm):

Set jumpers to EOL position if this device is the last node of the BACnet MS/TP network.

Jumper up = EOL not activated Jumper down = EOL activated

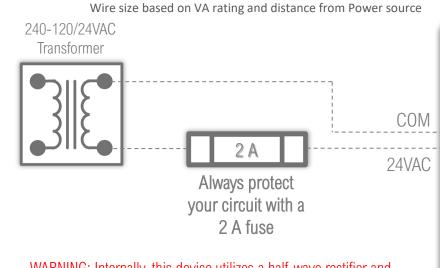




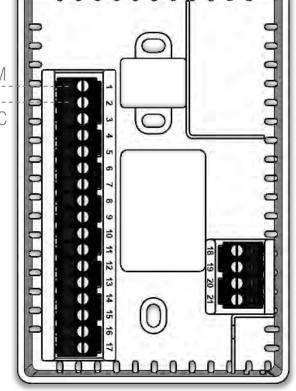
Add 24VAC transformer when the power is not supplied by the equipment

The BW437 must be powered using a Class 2, 24Vac transformer. When powering from a 24Vac transformer, do not ground either side of the transformer's secondary

For details on grounding within control panels, NFPA 79 and UL508A provide the required details.



WARNING: Internally, this device utilizes a half-wave rectifier and therefore can only share the same AC power source with other half-wave rectified devices. Sharing AC power with full wave rectified devices is NOT recommended. If not properly wired, connecting controllers on an MSTP BACnet network that have internal full wave rectifier controllers with Onyxx LX half-wave controllers can have adverse effect on network communications and in some cases would result in damaging the Onyxx LX Controllers. Not properly wiring the devices will void the warranty.

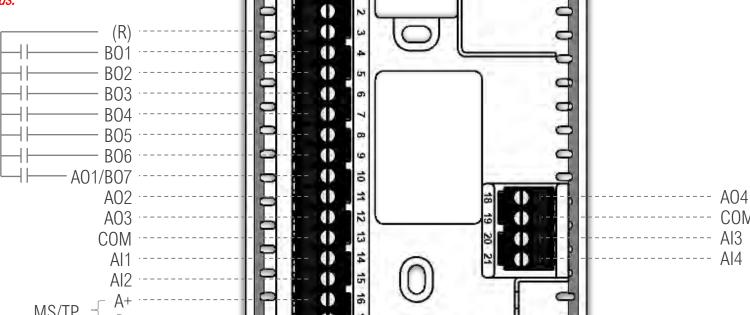


0 0 0 0 0 0 0 0 0





**recommend using pilot relays in any application utilizing Binary outputs as switching loads. **



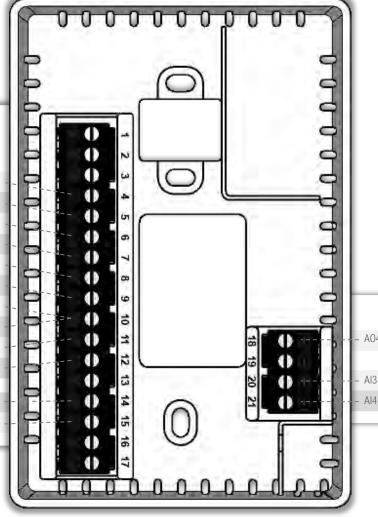


BY LYNXSPRING



Fan								
Variable speed	3 speeds	2 speeds	1 speed					
	High	High	High					
	Medium							
	Low	Low						
Enable								

	oipes	4	2 pipes		
	Floating	On/Off	Floating	On/Off	
B01	Open Cool	Cool NC valve	Open Cool/Heat	Heat NC valve	
B02	Close Cool	Cool NO valve	Close Cool/Heat	Heat NO valve	
B03	Open Heat	Heat NC valve			
B04	Close Heat	Heat NO valve	0-10v Aux/Reheat	0-10v Aux/Reheat	
B05					
B06					
B07					
A01					
A02		Cool		Cool/Heat	
A03		Heat			
Al1	Alarm1	Alarm1	Alarm1	Alarm1	
Al2	Alarm2	Alarm2	Alarm2	Alarm2	





ChangeOver SupplyT

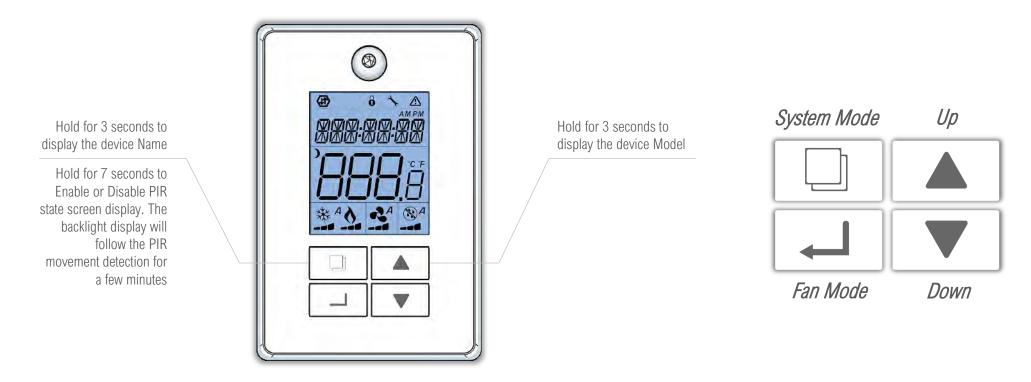
Remote Sensor Remote Sensor

Factory Program Terminal Functions





This section describes all the user adjustable interface functions of the BW437-FCU-LX





Please note that attempting to adjust the Setpoint using the arrows, in unoccupied mode, will automatically set the controller to Override / Day / Occupied mode





The signal icon indicates network connection status

Visible and fixed static = Online to both the BACnet MSTP network and the Strato Automation server Blinking = Online to the BACnet MSTP network only



The lock icon indicates that setpoints have been locked from the network and cannot be modified by the thermostat keys



The wrench icon indicates that the device is in configuration mode



The warning icon indicates that there may be MSTP communication errors / problem (invalid frames) Check wiring and use an MSTP sniffer tool if necessary



Displays whether the time is AM or PM



This line displays the room temperature or room setpoint
Use up and down arrows to temporarily modify the display setpoint



Displays the time (hh:mm) on the first line and the day of the week.



Icon to display night mode / unoccupied.



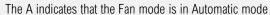
The water droplet icon indicates whether the dehumidification or humidification process is on and working

The segmented bar indicates whether the humidifier is at 33, 66 or 100% output capacity



The A indicates that the humidity function is in Automatic mode The fan icon indicates that fan is on and working

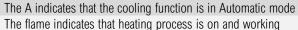
The segmented bars indicates whether the fan in 1st, 2nd or 3rd speed





The snowflake indicates that cooling process is on and working

The segmented bar indicates whether the cooling is at 33, 66 or 100% output capacity





The segmented bar indicates whether the heating is at 33, 66 or 100% output capacity

The A indicates that the heating function is in Automatic mode



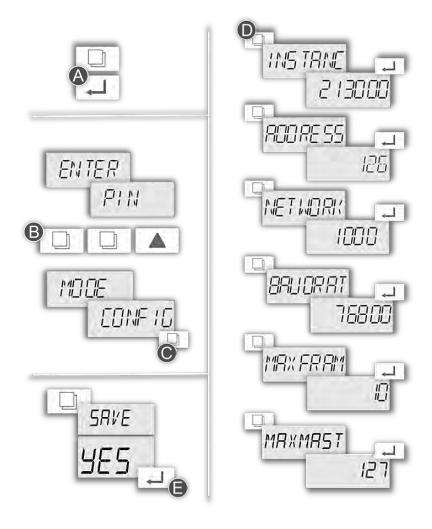


- A Set the BW437-FCU's configuration in the "CONFIG MODE" directly on the BW437-FCU's screen using the keypad. To be able to do so, press simultaneously and buttons for 3 seconds.
- B Press these PIN keys in sequence on the BW437-FCU's keypad CONFIG MODE will blink on the screen
- Press the button to start cycling thought the configuration menus.
- Press button to cycle through each parameter

 Access any configuration menu by pressing on the menu's display screen,

 Using the and the button, adjust each digit to the desired value.

 When done, press once more to confirm the new value.
- Accept to SAVE by selecting YES and pressing





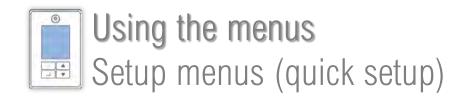


Using the menus

Setup menus (quick setup)



Access the "SETUP MENU" directly on the BW437FCU's screen using the keypad. To be able to do so, press simultaneously and buttons for 3 seconds. Press these PIN keys in sequence on the BW437FCU's keypad ENTER SETUP will appear on the screen for 1 second The first configurable object to be displayed in the SETUP menu is the PIPENUM PIN This is the one used for this next example The object name and the actual configuration will blink alternatively on screen. Note that the same steps apply to any other configurable object Use the ▲ ▼ to change the object SETUP configuration When the value is as wanted, press or to save the settings and switch to SETUP the next object To exit SETUP menu, scroll to the QUIT menu using Press when YES is displayed MSV52 MSV15 MSV58 BV75 MSV55 MSV54 MSV46 MSV47 MSV48 BV51 **B** SETUP VALVETL SEDOPER AI 1_EFG AIZ_EF6 RI3_CFG **C**TPENUM FAN_SED REHERT AUX_EF6 T_UNITS BUI NONE ON/OFF EBBLIN5 BASEBAD NE THORK NONE NONE IMPER 2 PIPES L-M-H-A 4F5 www.lynxspring.com



<i>Options</i> 2 Pipes	Function
2 Pines	
4 Pipes	Sets for a 2 pipes system where the same coil is used for heating and cooling Sets for a 4 pipes system with separate heating and cooling coils
On/Off Floating	Sets the system for using either NO or NC on/off control valves Sets the system for using floating type (Open/Neutral/Close) control valves
Cooling Heating	See cooling only sequence below See heating only sequence below
Cool-Rt Heat-Rt Cl-Ht	See cooling with reheat sequence below See heating with reheat sequence below See cooling / heating sequence below See cooling / heating with reheat sequence below
	Heat-Rt





Using the menus Setup menus (quick setup)

			- SETUP	
Object Instance	Setup menu	Description	Options	Function
MSV58	Fan_Seq	Control fan sequence	L-M-H L-H L-M-H-A L-H-A On-Auto	Sets the system for regular 3 speeds fan control (Low-Med-High) Sets the system for 2 speeds fan control (Low-High) Sets the system for 3 speeds fan control with automatic mode (Low-Med-High-Auto) Sets the system for 2 speeds fan control with automatic mode (Low-High-Auto) Sets the system for single speed fan control (On-Auto) On/Off or Modulating fan control
MSV55	Reheat	Reheat type	Basebrd Coil	Sets the reheat device as a perimeter heating equipment like a baseboard (water or electric) Sets the reheat device like an electric duct heater as a second stage of heat if needed
MSV54	Aux_CFG	Auxiliary output configuration	Reheat Occ-NO Occ-NC Fan-NO Fan-NC Network	Sets the reheat output BO4 to be used as a control reheat output as per MSV15 & 55 Sets the device output BO4 to follow the local occupancy mode where Occ=Closed Sets the device output BO4 to follow the local occupancy mode when fan is On Occ=Closed Sets output BO4 to follow the local occupancy mode when fan is On Occ=Closed Sets output BO4 to follow the local occupancy mode when fan is On Occ=Opened Sets the device output BO4 to follow object BV14 Aux_cmd





SETUP

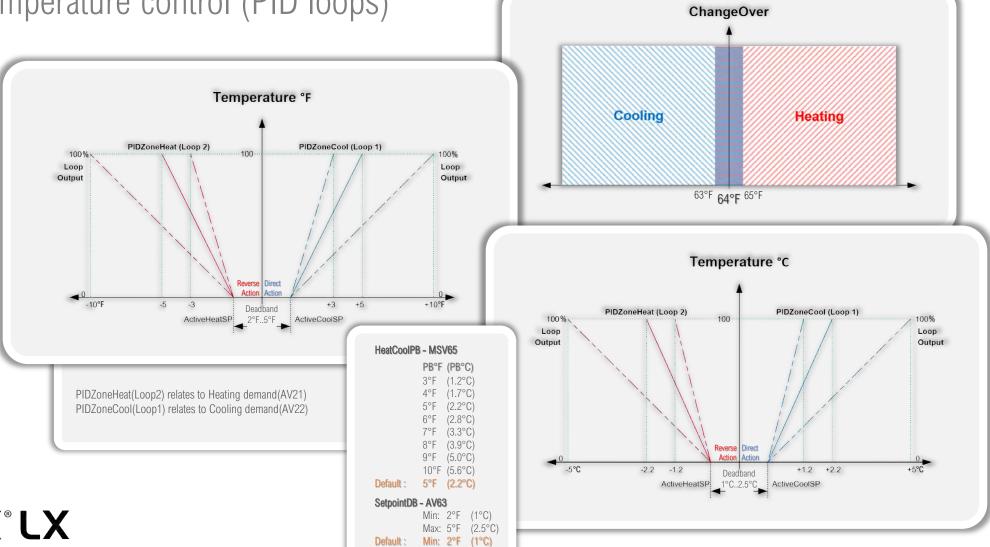
Object Instance	Setup menu	Description	Options	Function
MSV46	AI1_CFG	Analog input 1 configuration	None Rem NSB Mot-NO Mot-NC Window	Sets the configuration of Al1 to none. Analog status of input can still be read via Al1 object Sets the configuration of Al1 to use a remote time clock contact for occupancy Sets the configuration of Al1 to use a remote PIR sensor for occupancy where Closed=Occ Sets the configuration of Al1 to use a remote PIR sensor for occupancy where Opened=Unocc Sets the configuration of Al1 to use a remote window switch for automatic Unocc mode monitor with BV35
MSV47	AI2_CFG	Analog input 2 configuration	None DoorDry Overrid Filter Service	Sets the configuration of AI2 to none. Analog status of input can still be read via AI2 object Sets the configuration of AI2 to use a remote door switch for automatic Unocc mode with AI1=Windows Sets the configuration of AI2 to use a remote local override switch to by-pass Unocc mode Sets the configuration of AI2 to use a remote local pressure switch for filter status monitoring BV36 Sets the configuration of AI2 to use a remote local service contact for a local alarm display BV37
MSV48	AI3_CFG	Analog input 3 configuration	None COC/NH COC/NC COS SS	Sets the configuration of Al3 to none. Analog status of input can still be read via Al3 object Sets the configuration of Al3 to use a remote Normally Heat ChangeOverContact for a 2 pipes system Sets the configuration of Al3 to use a remote Normally Cool ChangeOverContact for a 2 pipes system Sets the configuration of Al3 to use a remote 10K changeover sensor for a 2 pipes system via AV13 object Sets the configuration of Al3 to use a remote monitoring 10K sensor via AV12 object





Application FCU – Typical Control Curves

Temperature control (PID loops)

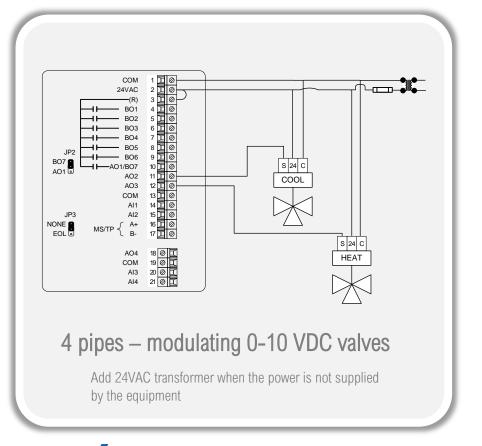




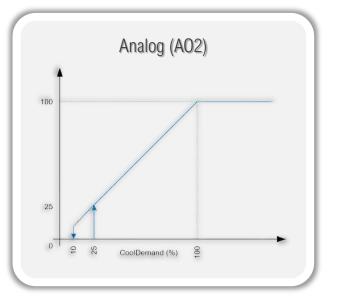


I/O Wiring & Sequence

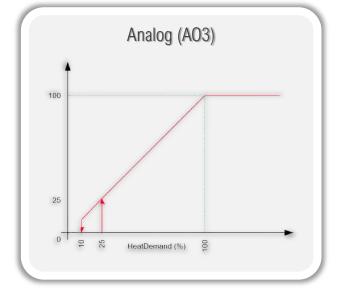
4 pipes – Modulating 0-10 VDC ValveS



Cooling demand > 25% for at least 180 seconds Mode is Auto or Cool (MSV16) Fan is running Window contact is Closed (BV35 if used)



Heating demand > 25% for at least 180 seconds Mode is Auto or Heat *(MSV16)* Fan is running Window contact is Closed *(BV35 if used)*



Sequence of operation

Occupied Mode: Setpoints will revert to those defined by occupied cooling and heating setpoints.

Stand-by Mode (only available when PIR models are used): Setpoints will revert to those defined by stand-by cooling and heating setpoints.

Unoccupied Mode: Setpoints will revert to those defined by unoccupied heating and cooling setpoints.

Occupied Override Mode: The system will revert to occupied mode for the duration determined by the "OvrTime" parameter

On a call for cooling: Cooling valve will modulate to maintain room temperature. Heating valve is closed.

On a call for heat: Heating valve will modulate to maintain room temperature. Cooling valve is closed.

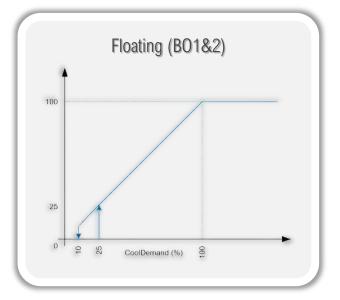




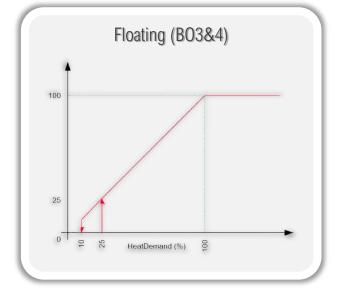
4 pipes – floating valves

4 pipes – floating valves Add 24VAC transformer when the power is not supplied by the equipment

Cooling demand > 25% for at least 180 seconds Mode is Auto or Cool (MSV16) Fan is running Window contact is Closed (BV35 if used)



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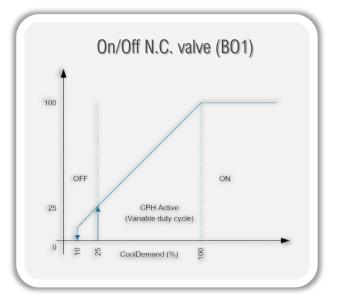
Inst I/O

Installation

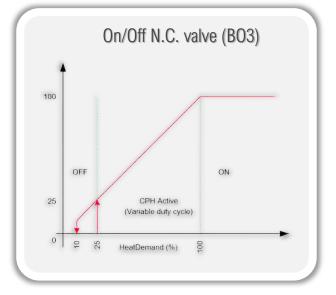
I/O Wiring & Sequence 4 pipes – on/off N.C. valves

COOL 4 pipes – on/off N.C. valves Add 24VAC transformer when the power is not supplied by the equipment

Cooling demand > 25% for at least 180 seconds Mode is Auto or Cool *(MSV16)* Fan is running Window contact is Closed *(BV35) if used*



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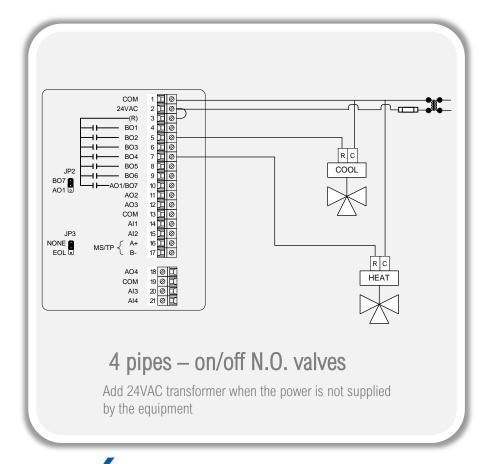
On a call for cooling: Cooling valve will open to maintain room temperature. Heating valve is closed.

On a call for heat: Heating valve will open to maintain room temperature. Cooling valve is closed.

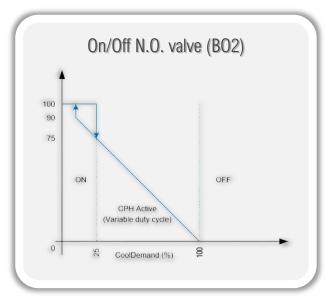


Installation I/O Wiring & Sequence

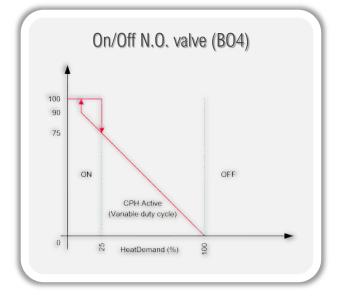
4 pipes – on/off N.O. valves



Cooling demand > 25% for at least 180 seconds Mode is Auto or Cool (MSV16) Fan is running Window contact is Closed (BV35) if used



Heating demand > 25% for at least 180 seconds Mode is Auto or Heat (MSV16) Fan is running Window contact is Closed (BV35) if used



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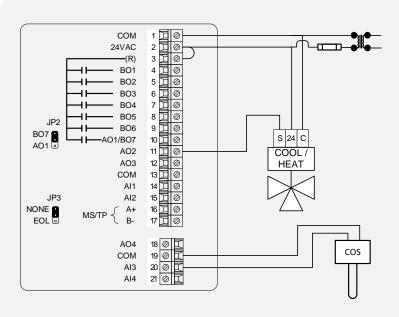
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I/O Wiring & Sequence 2 pipes – modulating 0-10 VDC valve



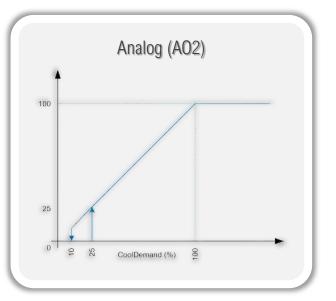
2 pipes – modulating 0-10 VDC valve

*COS: Change Over Sensor

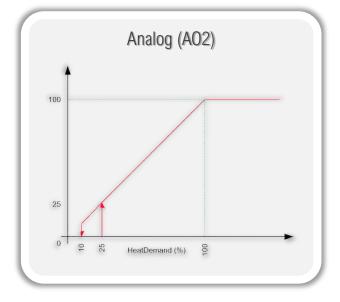
Add 24VAC transformer when the power is not supplied by the equipment

ONYX LX

Cooling demand > 25% for at least 180 seconds Mode is Auto or Cool (MSV16) Fan is running Window contact is Closed (BV35 if used)



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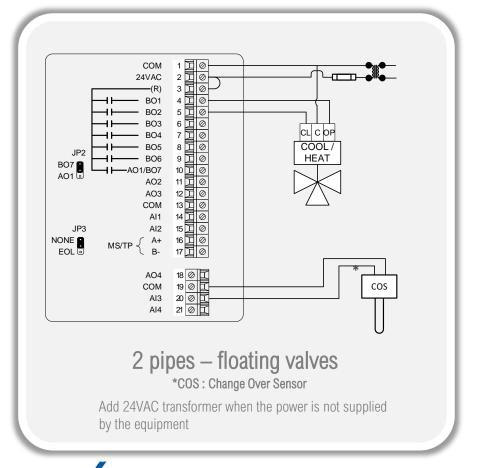
Occupied Override Mode: The system will revert to occupied mode for the duration determined by the "OvrTime" parameter

On a call for cooling: If the supply water temperature is less than 17.0°C (63F). Cooling valve will modulate to maintain room temperature. Heating valve is closed.

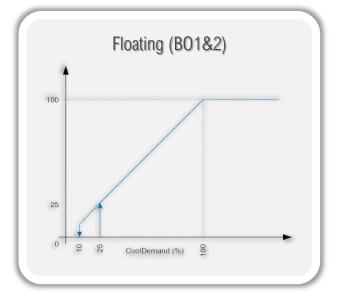
On a call for heat: If the supply water temperature is greater than 18.5°C (65F). Heating valve will modulate to maintain room temperature. Cooling valve is closed.



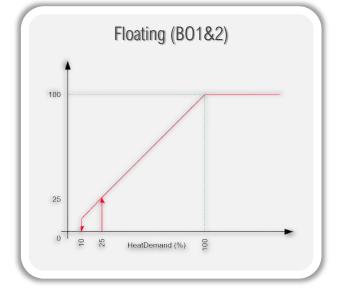
Installation I/O Wiring & Sequence 2 pipes – floating valves



Cooling demand > 25% for at least 180 seconds Mode is Auto or Cool (MSV16) Fan is running Window contact is Closed (BV35 if used)



Heating demand > 25% for at least 180 seconds Mode is Auto or Heat (MSV16) Fan is running Window contact is Closed (BV35 if used)



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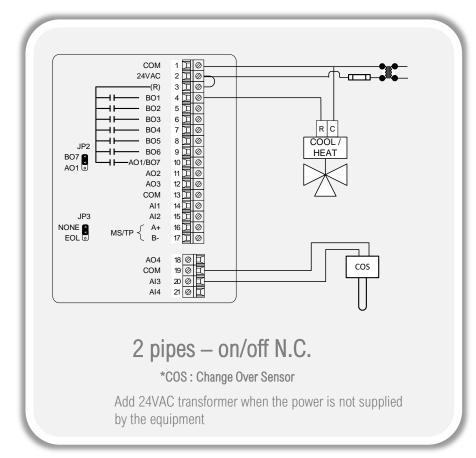
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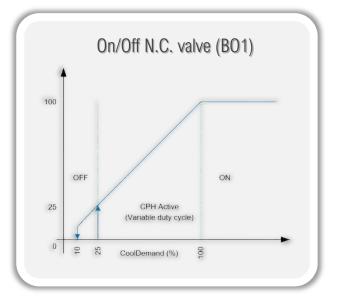




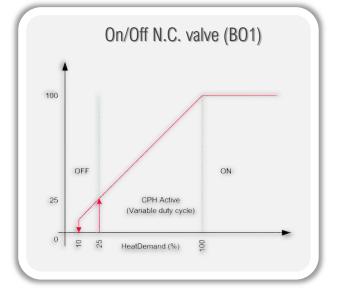
I/O Wiring & Sequence 2 pipes – on/off N.C.



Cooling demand > 25% for at least 180 seconds Mode is Auto or Cool *(MSV16)* Fan is running Window contact is Closed *(BV35) if used*



Heating demand > 25% for at least 180 seconds Mode is Auto or Heat (MSV16) Fan is running Window contact is Closed (BV35) if used



Sequence of operation

Occupied Mode: Setpoints will revert to those defined by occupied cooling and heating setpoints.

Stand-by Mode (only available when PIR models are used): Setpoints will revert to those defined by stand-by cooling and heating setpoints.

Unoccupied Mode: Setpoints will revert to those defined by unoccupied heating and cooling setpoints.

Occupied Override Mode: The system will revert to occupied mode for the duration determined by the "OvrTime" parameter

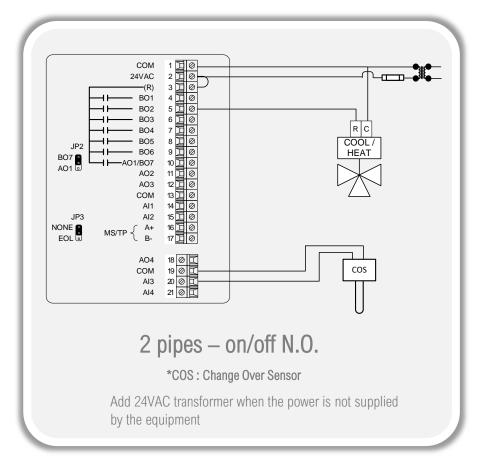
On a call for cooling: If the supply water temperature is less than 17.0°C (63F). Cooling valve will open to maintain room temperature. Heating valve is closed.

On a call for heat: If the supply water temperature is greater than 18.5°C (65F). Heating valve will open to maintain room temperature. Cooling valve is closed.

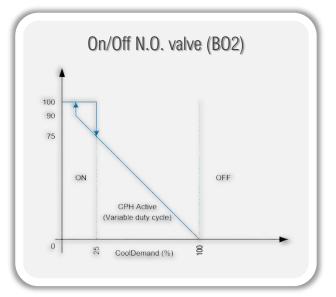




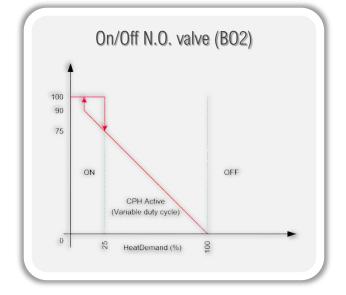
I/O Wiring & Sequence 2 pipes – on/off N.O.



Cooling demand > 25% for at least 180 seconds Mode is Auto or Cool (MSV16) Fan is running Window contact is Closed (BV35) if used



Heating demand > 25% for at least 180 seconds Mode is Auto or Heat (MSV16) Fan is running Window contact is Closed (BV35) if used



Sequence of operation

Occupied Mode: Setpoints will revert to those defined by occupied cooling and heating setpoints.

Stand-by Mode (only available when PIR models are used): Setpoints will revert to those defined by stand-by cooling and heating setpoints.

Unoccupied Mode: Setpoints will revert to those defined by unoccupied heating and cooling setpoints.

Occupied Override Mode: The system will revert to occupied mode for the duration determined by the "OvrTime" parameter

On a call for cooling: If the supply water temperature is less than 17.0°C (63F). Cooling valve will open to maintain room temperature. Heating valve is closed.

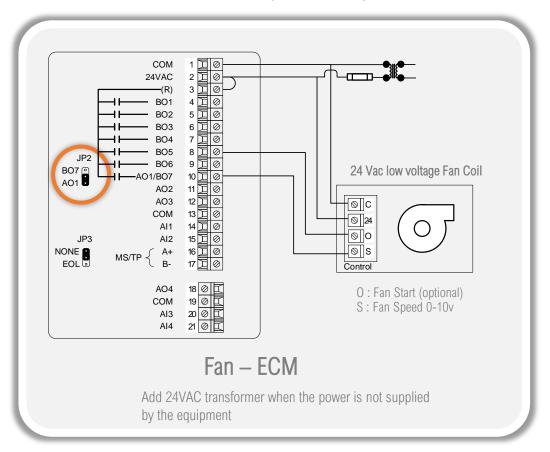
On a call for heat: If the supply water temperature is greater than 18.5°C (65F). Heating valve will open to maintain room temperature. Cooling valve is closed.





I/O Wiring & Sequence

Fan control – ECM (0-10VDC) MSV58 = On-Auto





Cooling demand > 25%

or

Heating demand > 25%

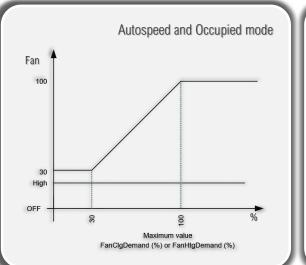
Fan mode: Auto

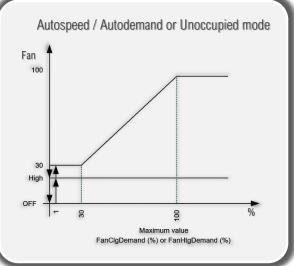
Cooling demand > 25%

or

Heating demand > 25%

Fan mode: Auto / Anti cycle of 1 second





Fan sequence of operation

Occupied Mode:

Fan = **Auto mode** will modulate the fan from the minimum set fan speed (AV25 ECM_min) to 100% at the same time as the main PI cooling and heating demand.

With the fan mode set to ON, the fan will drive directly to 100% demand.

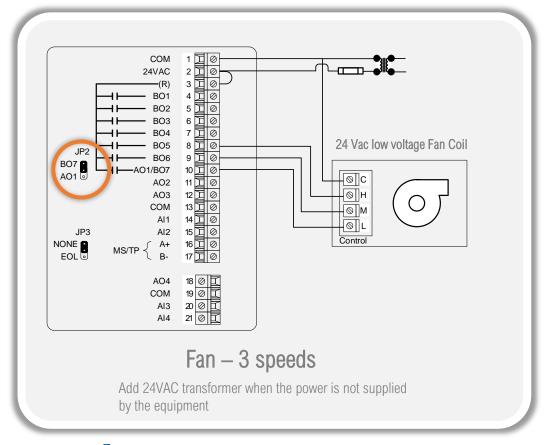
In the controller deadband between heating and cooling setpoints Autodemand (Keepfan BV66) = FanLow allows the fan to stay at the minimum set fan speed and (Keepfan BV66) = FanOff will shuts down the fan completely.

Stand-by & Unoccupied Mode:



I/O Wiring & Sequence

Fan control -3 speed fans MSV58 = L-M-H





Cooling demand > 25%

0

Heating demand > 25%

10

Occupied mode Fan mode: Auto

Anti cycle of 1 second

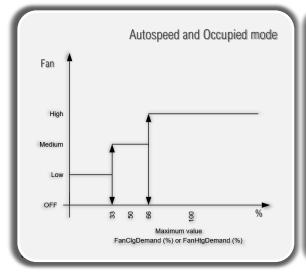


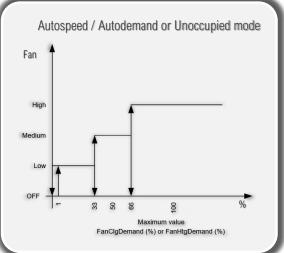
10

Heating demand > 25%

Fan mode : Auto

Anti cycle of 1 second





Occupied Mode:

Fan = **Auto mode** will modulate the fan from low to high speed the same time as the main PI cooling and heating demand.

With the fan mode set to Low, the fan will drive to Low speed.

With the fan mode set to Medium, the fan will drive to Medium speed.

With the fan mode set to High, the fan will drive to High speed.

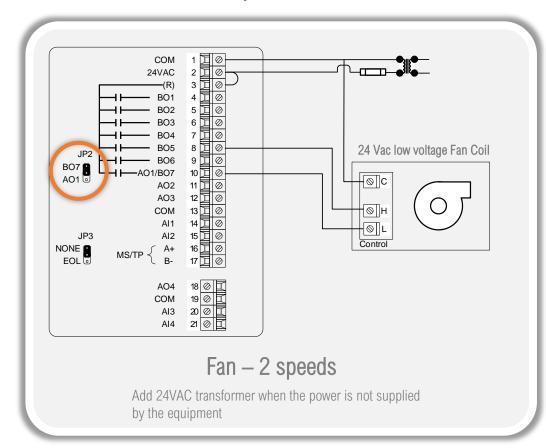
In the controller deadband between heating and cooling setpoints Autodemand (Keepfan BV66) = FanLow allows the fan to stay at Low fan speed and (Keepfan BV66) = FanOff will shuts down the fan completely.

Stand-by & Unoccupied Mode:



I/O's Wiring & Sequence

Fan control -2 speed fans MSV58 = L-H





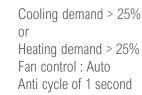
Cooling demand > 25%

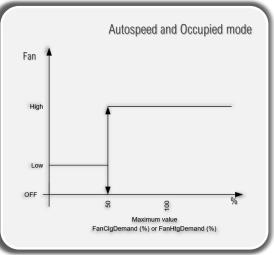
Heating demand > 25%

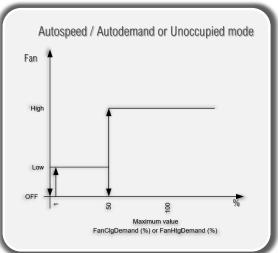
Occupied mode

Anti cycle of 1 second









Fan sequence of operation

Occupied Mode:

Fan = Auto mode will modulate the fan from low to high speed the same time as the main PI cooling and heating demand.

With the fan mode set to **Low**, the fan will drive to Low speed. With the fan mode set to High, the fan will drive to High speed.

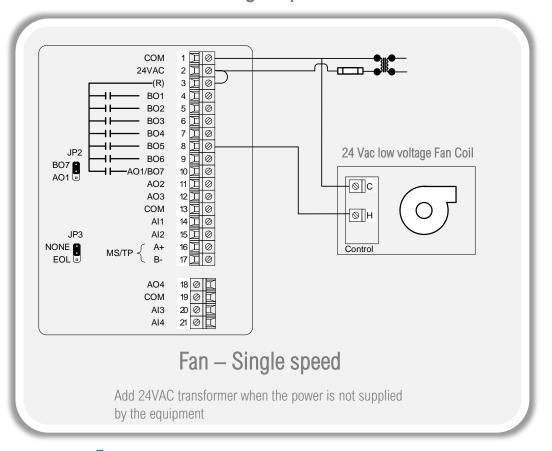
In the controller deadband between heating and cooling setpoints Autodemand (Keepfan BV66) = FanLow allows the fan to stay at Low fan speed and (Keepfan BV66) = FanOff will shuts down the fan completely.

Stand-by & Unoccupied Mode:



I/O Wiring & Sequence

Fan control – single speed fans MSV58 = On-Auto



Fan sequence of operation

Occupied Mode:

Fan = Auto mode will energize the fan when the main PI cooling and heating demands are above 1% demand.

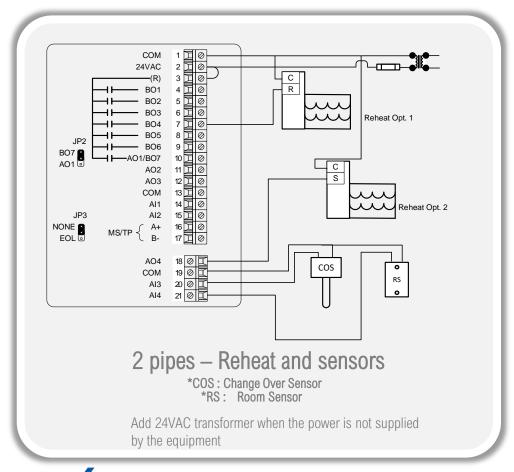
With the fan mode set to \mathbf{ON} , the fan will energize all the time during Occupied periods.

In the controller deadband between heating and cooling setpoints, Autodemand (Keepfan BV66) = FanLow allows the fan to stay ON and (Keepfan BV66) = FanOff will shuts down the fan completely.

Stand-by & Unoccupied Mode:

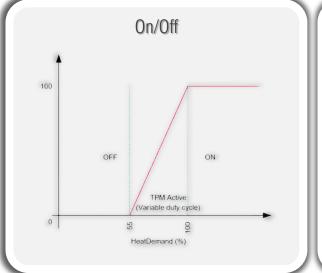


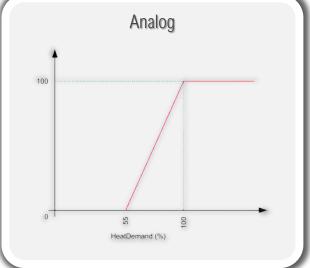
Installation I/O Wiring & Sequence



Call For Heating for at least 180 seconds
Fan is running
Reheat is allowed
MSV54 = Reheat

Call For Heating for at least 180 seconds Fan is running Reheat is allowed MSV54 = Reheat





Reheat operation

Only valid if MSV15 (Sequence of Operation) is set to a Reheat sequence: Cool-Rt, Heat-Rt or Cool-Heat-Rt

Occupied, Stand-by & Unoccupied Mode:

The Reheat stage can either be modulating 0-10 VDC / AO4 or On/Off BO4. The Reheat stage will be used as the main heating device if the system main water for the FCU is cold water and will be used as a second heating stage if the system main water for the FCU is hot water water

A typical reheat device in some area used in conjunction with an FCU can even be a separate baseboard heating unit

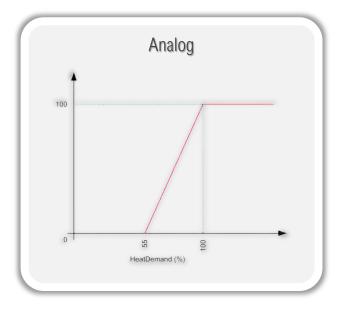


BY LYNXSPRING

Installation I/O Wiring & Sequence

AI2 NONE 18 Ø 14-19 Ø 14-20 Ø 14-21 Ø 14 SS 4 pipes – Reheat and sensors *SS: Supply Sensor *RS: Room Sensor Add 24VAC transformer when the power is not supplied by the equipment

Call For Heating for at least 180 seconds
Fan is running
Reheat is allowed
MSV54 = Reheat



Reheat operation

Only valid if MSV15 (Sequence of Operation) is set to a Reheat sequence: Cool-Rt, Heat-Rt or Cool-Heat-Rt

Occupied, Stand-by & Unoccupied Mode:

The Reheat stage is 0-10 Vdc / AO4 only. The Reheat stage will be used as the main heating device if the system main water for the FCU is cold water and will be used as a second heating stage if the system main water for the FCU is hot water water

A typical reheat device in some area used in conjunction with an FCU can even be a separate baseboard heating unit





Using the menus

Service menus / Allows Keypad Access to all Objects

PHYS IO

RIV

Bl/

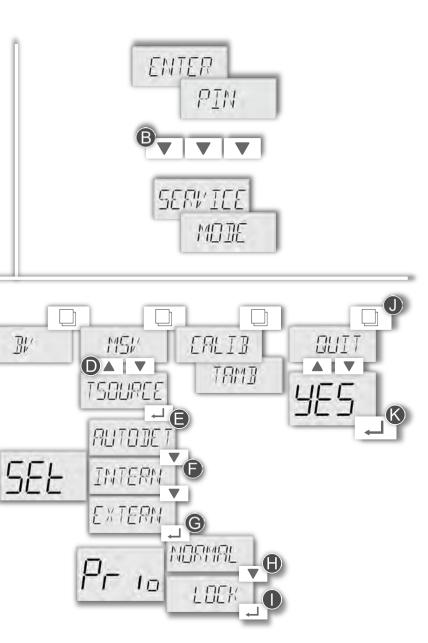
- Access the "Service menus" directly on the BW437-FCU's screen using the keypad. To be able to do so, press simultaneously and buttons for 3 seconds.
- Press these PIN keys in sequence on the BW437FCU's keypad "SERVICE MODE" will blink on the screen
- Use the button to scroll through the list of menus
- to scroll trough a category of objects
- Press on any object to access its configurable settings
- Use the ▲ ▼ to scroll trough the settings
- Once your setting is selected, press | 📥 | to access the Priority screen
- Use the
 to select the objects priority
- Once your priority is selected, press \leftarrow to confirm your choice
- To exit SERVICE MODE, press of for 3 seconds to access the QUIT screen
- Using the ▲ ▼ press → when "YES" is displayed

Notes:

Please refer to the object list tables below for a reference on each objects and their available selection

The typical priority set at stage (1) is "Normal"







Using the menus

Test IO mode menu / Allows Local Testing of I/O's

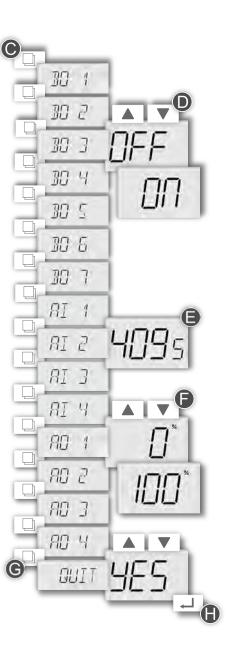
- Access the "Test IO mode" directly on the BW437's screen using the keypad. To be able to do so, press simultaneously and buttons for 3 seconds.
- B Press these PIN keys in sequence on the BW437FCU's keypad "TEST IO MODE" will blink on the screen
- O Use the button to scroll through the list of IO's
- Use the ▼ to change the binary output object state
- Al reading goes from 0 to 4095 (raw count value / not adjustable)
- Use the ▼ to change the analog output object value
- G To exit TEST IO MODE, scroll to the QUIT menu using
- Using the , press when "YES" is displayed



Notes:

Exiting the Test IO mode will revert the controller to its normal state of operation as per the configuration used







Physical Inputs and Outputs (Al's, AO's, BI's & AO's)

PHYS ID

Object Instance	FCU Object name	Description	Default value	Tags	Minimum range value	Maximum range value	Inactive_Text	Active_Text
<i>BO1</i>	BO_1	Binary output 1	Off	Status			Off	On
B02	BO_2	Binary output 2	On	Status			Off	On
<i>BO3</i>	BO_3	Binary output 3	Off	Status			Off	On
BO4	BO_4	Binary output 4	On	Status			Off	On
<i>B05</i>	BO_High	High speed fan output	Off	Status			Off	On
<i>B06</i>	BO_Med	Medium speed fan output	Off	Status			Off	On
B07	BO_Low	Low speed fan output	Off	Status			Off	On
A01	AO_ECM	Fan ECM output	0%	Status	0%	100%		
A02	A0_2	Analog output 2	0%	Status	0%	100%		
A03	AO_3	Analog output 3	0%	Status	0%	100%		
A04	AO_4	Auxiliary / Reheat output	0%	Status	0%	100%		
Al1	AI_1	Analog input 1		Status	Based on A	I1_cfg object MSV46		
AI2	AI_2	Analog input 2		Status	Based on A	I2_cfg object MSV47		
AI3	AI_3	Analog input 3		Status	Based on A	I3_cfg object MSV48		
A/4	AI_4	Remote sensor		Status				
A15	RoomT	Room temperature	N/A	Status	32°F (0°C)	122°F (50°C)		
A16	RoomRH	Room humidity	N/A	Status	5%	90%		

Status

Status

0 PPM

2000 PPM

Off

Use JP2 jumper to choose between BO7 or AO1



Please note that objects tagged as:

RoomCO2

Motion

A/7

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Room CO2

Motion detection

Active



Analog Values



Object Instance	FCU Object name	Description	Tags	Default value	Minimum range value	Maximum range value
AV1	RoomTSP	Room Temperature setpoint	User	72°F (22°C)	54°F (12°C)	90°F (32°C)
AV7	Eff_T	Effective temperature used for control	Status		-40°F (-40°C)	122°F (50°C)
AV9	OATemp	Outdoor air temperature	Status		-40°F (-40°C)	122°F (50°C)
AV12	SATemp	Supply air temperature	Status		-40°F (-40°C)	122°F (50°C)
AV13	CHOV_T	Changeover temperature	Status		-40°F (-40°C)	122°F (50°C)
AV21	HTG_Dem	Heating demand	Status		0%	100%
AV22	CLG_Dem	Cooling demand	Status		0%	100%
AV23	Fan_HTDemand	Fan heating demand	Status		0%	100%
AV24	Fan_CLDemand	Fan cooling demand	Status		0%	100%
AV25	ECM_Min	ECM minimum speed output	Cfg	30%	0%	100%
AV30	EffHTSP	Effective heating setpoint	Status	71°F (21°C)		
AV31	EffCLSP	Effective cooling setpoint	Status	73°F (23°C)		
AV39	OccHTSP	Occupied heating setpoint	User	71°F (21°C)		
AV40	OccCLSP	Occupied cooling setpoint	User	73°F (23°C)		
AV41	STBHTSP	Standby heating setpoint	Cfg	69°F (20.5°C)		
AV42	STBCLSP	Standby cooling setpoint	Cfg	78°F (25.5°C)		
AV43	Unoc_HT_SP	Unoccupied heating setpoint	Cfg	62°F (16.5°C)		
AV44	Unoc_CL_SP	Unoccupied cooling setpoint	Cfg	80°F (26.5°C)		
AV50	RT_Cal	Room temperature calib	Cfg	0°(C/F)	-3°(C/F)	3°(C/F)
AV58	MaxHTSP	Maximum heating setpoint	Cfg	90°F (32°C)	40°F (4.5°C)	90°F (32°C)
AV59	MinCLSP	Minimum cooling setpoint	Cfg	54°F (12°C)	54°F (12°C)	100°F (37.5°C)
AV63	SP_DB	Setpoint deadband	Cfg	2°F (1°C)	2°F (1.1°C)	5°F (2.8°C)
AV67	StandbyDLY_Hrs	Standby time delay	Cfg	0.5 Hour	0.5 Hour	24.0 Hours
AV68	Unoc_T_DLY_Hrs	Unoccupied time delay	Cfg	0.0 Hour	0.0 Hour	24.0 Hours



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Binary Values



Object Instance	FCU Object name	Description	Tags	Default value	Inactive_Text	Active_Text
BV1	SaveObj	Save all objects to flash	Cfg	Normal	Normal	Save
BV8	OVRSTAT	Occupancy override status	Status	Normal	Normal	Overrid
BV14	Aux_Cmd	Auxiliary network command	Cmd	Off	Off	On
<i>BV25</i>	AuxStat	Auxiliary output status	Status	Off	Off	On
BV29	Al1Stat	Analog input 1 binary contact status	Status	Deactivated	Deactivated	Activated
BV30	AI2Stat	Analog input 2 binary contact status	Status	Deactivated	Deactivated	Activated
BV31	Al3Stat	Analog input 3 binary contact status	Status	Deactivated	Deactivated	Activated
BV32	Mot_Det	Motion detection	Status	Moving	None	Moving
<i>BV35</i>	Window	Window detection status	Status	Close	Close	Open
<i>BV36</i>	Filter	Filter sensor status	Status	Normal	Normal	Alarm
<i>BV37</i>	ServALM	Service alarm status	Status	Normal	Normal	Alarm
BV40	Ch_Over	Change over status	Status	Cool	Cool	Heat
BV50	AutoMod	Auto mode authorised	Cfg	Yes	No	Yes
BV51	T_Units	Temperature units	Cfg	Imper	Imper	Metric
BV64	Reh_Opt	Reheat control option	Cfg	Pulse1S	Pulse1S	On/Off
BV66	KeepFan	Fan auto mode	Cfg	Fan Low	Fan Low	Fan Off
<i>BV75</i>	VALVCTL	Valve motors control type	Cfg	On/Off	On/Off	Floatng
BV78	AO2_Dir	AO2 action	Cfg	Direct	Direct	Reverse
<i>BV79</i>	AO3_Dir	AO3 action	Cfg	Direct	Direct	Reverse



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1451/

	Object Instance	FCU Object name	Description	Tags	Default value	State texts
	Tsource	Temperature input location	Cfg	AutoDet	AutoDet Intern Extern	
	MSV15	SeqOper	Control sequence of operation	Cfg	CI-Ht	Cooling Heating Cool-Rt Heat-Rt CI-Ht CI-Ht-R
	MSV16	MODE	System mode	User	Off	Off Auto Cool Heat
	MSV17	FAN	Fan mode	User	Auto	Lo Med Hi Auto
	MSV18	Occ_Cmd	Occupancy command	Cmd	Loc_Occ	Loc_Occ Occupied Unoccup



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MEN

Object Instance	FCU Object name	Description	Tags	Default value	State texts
MSV19	KeyLock	Keypad lock level	Cfg	None	None Fan Mode FanMode All
MSV26	B03_B04	BO3/BO4 status	Status	Close	Stopped Open Close
MSV27	B01_B02	B01/B02 status	Status	Close	Stopped Open Close
MSV28	FanStat	Fan status	Status	Off	Off Low Med High
MSV33	Eff_Occ	Effective occupancy mode	Status	Occupied	Occupied Unoccup TempOcc Standby



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Object Instance	FCU Object name	Description	Tags	Default value	State texts
MSV46	AI1_CFG	Analog input 1 configuration	Cfg	None	None
					Rem NSB
					Mot-NO
					Mot-NC
					Window
MSV47	AI2_CFG	Analog input 2 configuration	Cfg	None	None
					Door Dry (door switch)
					Overrid (remote local override switch)
					Filter
					Service
MSV48	AI3_CFG	Analog input 3 configuration	Cfg	None	None
					COC/NH (Normally Heat ChangeOverContactfor)
					COC/NH (Normally Cool ChangeOverContactfor)
					COS (Change over Sensor)
					SS (remote monitoring 10K sensor)
MSV52	PipeNum	Pipe number	Cfg	4 Pipes	2 Pipes
					4 Pipes
MSV54	Aux_CFG	Auxiliary output configuration	Cfg	Reheat	Reheat
					Occ-NO
					Occ-NC
					Fan-NO
					Fan-NC
					Network



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MEL

Object Instance	FCU Object name	Description	Tags	Default value	State texts
MSV55	Reheat	Reheat type	Cfg	Basebrd	Basebrd Coil
MSV58	Fan_Seq	Control fan sequence	Cfg	On-Auto	L-M-H L-H L-M-H-A L-M-H On-Auto
MSV61	Occ_Opt	Occupancy options schedule or motion	Cfg	None	No S_and_M S_or_M Sc-Only
MSV62	OvrTime	Override time delay	Cfg	2 hours	0 - 24 hours
MSV65	PB	Heating / cooling proportional band	Cfg	5 F 2.2 C	3 F (1.2 C) - 10 F (5.6 C)
MSV70	SP_AUTO	Zone Temperature setpoint in auto mode	Cfg	Center	Heating Center Cooling
MSV75	BO3Time	BO3/BO4 travel time for 3 states valve	Cfg	1.5 minutes	0.5 min - 6 min
MSV76	BO1Time	BO1/BO2 travel time for 3 states valve	Cfg	1.5 minutes	0.5 min - 6 min
MSV77	CL_CPH	Cooling output cycle per hour	Cfg	4 CPH	3 - 8 CPH
MSV78	HT_CPH	Heating output cycle per hour	Cfg	4 CPH	3 - 8 CPH



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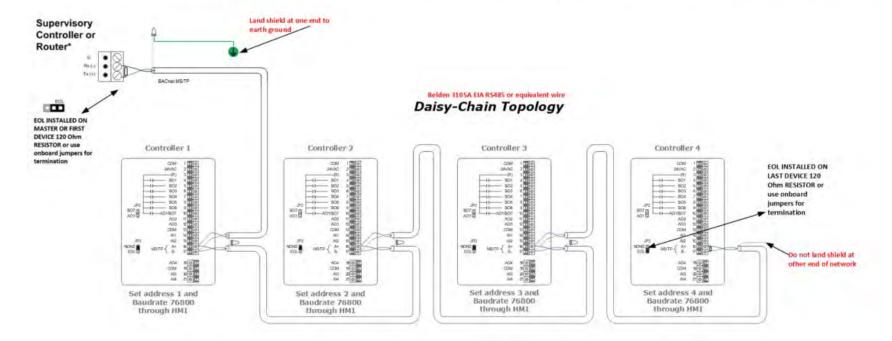
RS-485 Network Guidelines BW Controllers

The best way to ensure a robust and reliable RS-485 network is to build it around a daisy-chain configuration.

Connecting a multidrop 485 network.

The EIA RS-485 Specification labels the data wires "A" and "B", but many manufacturers label their wires "+" and "-". In our experience, the "+" wire should be connected to the "A" line, and the "-" wire to the "B" line. Reversing the polarity will not damage a 485 device, but it will not communicate. This said, the rest is easy: always connect + to + and - to -.

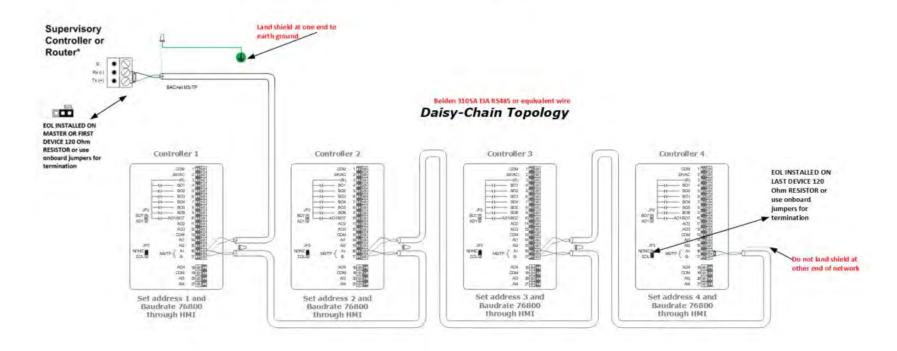
Signal ground, don't forget it. While a differential signal does not require a signal ground to communicate, the ground wire serves an important purpose. Over a distance of hundreds or thousands of feet there can be very significant differences in the voltage level of "ground." The function of the signal ground wire is to the the signal ground of each of the nodes to one common ground. If the ground voltage rises above 3 Vac, data will be lost and often the port itself will be damaged. However, if the differences in signal grounds is too great, further attention is necessary.







RS-485 Network Guidelines BW Controllers



Troubleshooting tips for 485 networks

- 1. Ensure that the communication wire is Belden 3105A or equivalent [twisted shielded pair].
- 2. Ensure your polarity is validated on both sides of your coms cable at each device + to + and to -.
- 3. Ensure you have a 120 ohm resistor on both your beginning master device and your last device (or onboard jumpers).
- 4. Ensure your shield is grounded only at one side and the source is a true earth ground [et. Building steel/beam, dedicated ground].
- 5. Make sure you are individually addressed on each device.
- 6. Make sure your Baud Rate is the same on all devices.



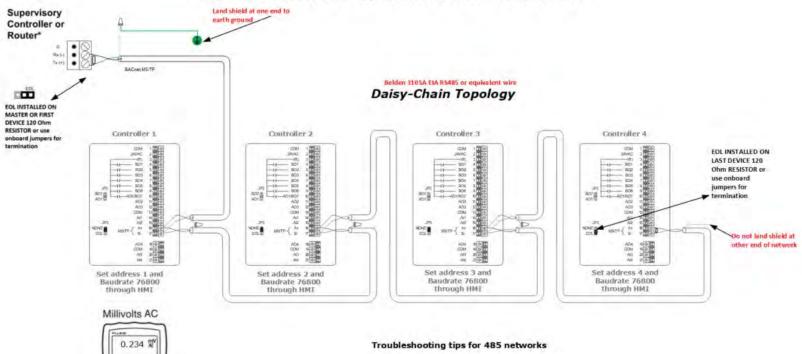


RS-485 Network Guidelines BW Controllers Land shield at one end to Supervisory earth ground Controller or Router* BACmet MS/TP Belden 3105A EIA R5485 or equivalent wire Daisy-Chain Topology EOL INSTALLED ON MASTER OR FIRST **DEVICE 120 Ohm** RESISTOR or use Controller 1 Controller 2 Controller 3 Controller 4 anboard jumpers for termination **EOL INSTALLED ON** 28/AC - 901 - 901 - 903 - 904 - 100 - 100 - 401907 - ACI LAST DEVICE 120 Ohm RESISTOR or use onboard jumpers for o not land shield at ACI 10 8 T COM 10 0 T ALL 2 6 T ADA COM AD AM other end of network Set address 3 and Set address 4 and Set address 1 and Set address 2 and Baudrate 76800 Baudrate 76800 Baudrate 76800 Baudrate 76800 through HMI through HMI. through HMI Volts DC Volts DC 2.512 ∞ -2.512 = Troubleshooting tips for 485 networks 1. On a connected RS-485 network, measure with your RMS multi-meter from either + or - to earth ground. You should read about 2.5Vdc, if you are higher than 2.75Vdc you are encountering noise and you either do not have a shielded twisted pair cable or you have a grounded shield at both sides or the integrity of your cable is compromised. If you are reading lower than 2.1Vdc than you have a device on your network or front end that is limiting the biasing circuit or you have a device that is causing an issue, no termination on both ends of the network, etc..





RS-485 Network Guidelines BW Controllers

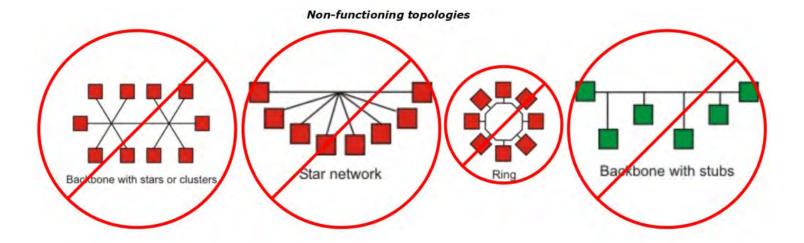


 Measure with your multi-meter from + to - with your RS-485 network connected. You should read between 200m/Vac to 600m/Vac average. If you read greater than 700m/Vac average then you may have a device that is compromising your network or you do not have your shield landed in one location or your controller grounded.





RS-485 Network Guidelines BZ Controllers





BY LYNXSPRING



Technical Specifications

Power supply:

24 VAC/VDC ± 15%; Class 2

Current consumption:

- 1.5 VA controller only
- 96 VA Max (including outputs 0.5A each)

Communication protocols:

- BACnet MS/TP
- BTL listed: B-ASC, BACnet Application Specific Controller
- Baud 9600, 19200, 38400, 76800 Bps (76800 default)
- Addressing: Keypad configuration
- Mini USB2 MS/TP network access (USB-485 Cable Adapter)

Hardware

- Microprocessor: STM32 (ARM CortexTM M3) 32 bits,
- CPU Speed: 72MHz
- . Memory: 768 KB non-volatile Flash
- · (application program)
- RAM: 96 KB RAM
- Real-time clock (RTC): Built-in capacitor (one-week backup)

Backlight display / LCD

 Multi-HVAC system symbols, time display, four-segment main numeric display with one decimal

Programming:

 Configurable with the Onyxx LX UI Software

Inputs:

- 4 Universal Inputs (AI/BI)
- Thermistor 10KΩ (type 2 or 3)
- Dry contact, 500 ms minimum (On-Off)
 Voltage 0 10 Vdc (Input impedance of
- 100 K Ω)
 Resolution: 12 Bits (4096 segments)

Outputs:

6 Binary Outputs

- Mosfet Solid State Relays, Isolated
- 10 to 30VAC/VDC, 0.5A max

3 Analog Outputs

Voltage 0 - 10 Vdc linear

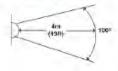
1 Universal AO/DO's

- Jumper selectable
- · Same specification as above

Humidity sensor: Sensirion SHT31 ±2 @ 0-100% RH

PIR sensor

- Operating Principle: Passive Infrared
- Detection Angle: 100 degrees
- Detection Distance: 4M (13ft) maximum
- Detection Area



CO2 sensor: Sensirion SCD30

- Self-calibrating, non-dispersive infrared (NDIR)
- Sensor Range: 0-5000 PPM
- . Accuracy: ± 30 PPM @ 3% of reading
- Accuracy is valid after a minimum of 3 weeks of continuous operation
- Response Time T63: 2 minutes

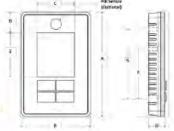
Mechanical:

- Dimensions: B 3.25" x A 4.88" x 0.8"
 B 83 mm x A 124 mm x 20 mm
- Stocking temperature:
 -30 °C to 50 °C / -22 °F to 122 °F
- Operating conditions:
 -25 °C to 50 °C / -13 °F to 113 °F
 10% to 90% H.R. without condensation
- Weight: 120 g / 0.25 lb
- Mounting type: Standard 2" x 4" electrical junction box
- Enclosure: White color, ABS material UL94VO

Warranty: 1 year

Certifications:

- UL 916 Energy Management Equipment
- BTL listed: B-ASC, BACnet Application Specific Controller



WARNING: Internally, this device utilizes a half-wave rectifier and therefore can only share the same AC power source with other half-wave rectified devices.

