## **IB IL AI 2/SF-ME**

Inline, analog input terminal, 2 inputs for connecting voltage or current signals



Data sheet 7037\_en\_02

© PHOENIX CONTACT 2019-03-06

## 1 Description

The terminal is designed for use within an Inline station. It is used to acquire analog voltage and current signals.

#### **Features**

- 2 analog single-ended signal inputs for the connection of either voltage or current signals
- Connection of sensors in 2-wire technology
- Current ranges: 0 mA ... 20 mA, 4 mA ... 20 mA, ±20 mA
- Voltage ranges: 0 V ... 10 V, ±10 V
- Channels are parameterized independently of one another via the bus system
- Measured values can be represented in four different formats
- Resolution: 12 bits + sign bit
- Process data update of both channels within a max. of 1.5 ms



This data sheet is only valid in association with the IL SYS INST UM E user manual.



Make sure you always use the latest documentation.

It can be downloaded at: phoenixcontact.net/product/2863944



<b>2</b> 1	Table of contents  Description	1
2	Table of contents	2
3	Ordering data	3
4	Technical data	
5	Additional technical data	6
6	Tolerance data	7 7
7	Internal circuit diagram	8
8	Electrical isolation	8
9	Terminal point assignment	9
10	Installation instructions	9
11	Connection notes	9
12	Connection examples  12.1 Connection of active sensors  12.2 Connection of passive sensors  12.3 Connecting a battery monitor	11 11
13	Local diagnostic and status indicators	12
14	Process data	13
15	Formats for representing measured values  15.1 IB IL format  15.2 IB ST format  15.3 IB RT format  15.4 Standardized representation format  15.5 Supported error codes for IB IL and standardized representation formats  15.6 Example	15 16 17 18
	15.7 Assignment of the terminal points to IN process data	

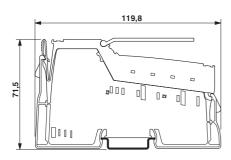
## 3 Ordering data

Description	Туре	Order No.	Pcs./Pkt.
Inline, analog input terminal, analog inputs: 2, 0 V 10 V, -10 V 10 V, 0 mA 20 mA, 4 mA 20 mA, -20 mA 20 mA, connection method: 2-wire, transmission speed in the local bus: 500 kbps, degree of protection: IP20, including Inline connector and labeling field	IB IL AI 2/SF-ME	2863944	1

Accessories	Туре	Order No.	Pcs./Pkt.
Labeling field, width: 12.2 mm (Marking)	IB IL FIELD 2	2727501	10
Insert strip, Sheet, white, unlabeled, can be labeled with: Office printing systems: Laser printer, mounting type: insert, lettering field size: 62 x 10 mm (Marking)	ESL 62X10	0809492	1
Documentation	Туре	Order No.	Pcs./Pkt.
<b>Documentation</b> User manual, English, Automation terminals of the Inline product range	Type IL SYS INST UM E	Order No.	Pcs./Pkt.

## 4 Technical data

## Dimensions (nominal sizes in mm)



Width	12.2 mm
Height	119.8 mm
Depth	71.5 mm
Note on dimensions	Housing dimensions

7037\_en\_02 PHOENIX CONTACT 3 / 19

General data	
Color	green
Weight	52 g (with connector)
Operating mode	Process data operation with 2 words
Ambient temperature (operation)	-25 °C 55 °C
Ambient temperature (storage/transport)	-25 °C 85 °C
Permissible humidity (operation)	10 % 95 % (non-condensing)
Permissible humidity (storage/transport)	10 % 95 % (non-condensing)
Air pressure (operation)	70 kPa 106 kPa (up to 3000 m above sea level)
Air pressure (storage/transport)	70 kPa 106 kPa (up to 3000 m above sea level)
Degree of protection	IP20
Protection class	III, IEC 61140, EN 61140, VDE 0140-1
Connection data: Inline connector	
Connection method	Spring-cage connection
Conductor cross section solid / stranded	$0.08 \text{ mm}^2 \dots 1.5 \text{ mm}^2 / 0.08 \text{ mm}^2 \dots 1.5 \text{ mm}^2$
Conductor cross section [AWG]	28 16
Stripping length	8 mm
Connection data for UL approvals: Inline con	nector
Connection method	Spring-cage connection
Conductor cross section solid / stranded	0.2 mm <sup>2</sup> 1.5 mm <sup>2</sup> / 0.2 mm <sup>2</sup> 1.5 mm <sup>2</sup>
Conductor cross section [AWG]	24 16
Stripping length	8 mm
Interface: Inline local bus	
Number	2
Connection method	Inline data jumper
Transmission speed	500 kbps
Communications power (U <sub>L</sub> )	
Supply voltage	7.5 V DC (via voltage jumper)
Current draw	typ. 45 mA max. 60 mA
Supply of analog modules (U <sub>ANA</sub> )	
Supply voltage	24 V DC (via voltage jumper)
Supply voltage range	19.2 V DC 30 V DC (including all tolerances, including ripple)
Current draw	typ. 13 mA max. 18 mA
Power consumption	
Power consumption	typ. 662 mW max. 882 mW

7037\_en\_02 PHOENIX CONTACT 4/19

Analog inputs	
Number of inputs	2
Description of the input	Single-ended inputs, voltage or current
Connection method	Inline connector
Connection technology	2-wire
6,5	
Current input signal	0 mA 20 mA, 4 mA 20 mA, -20 mA 20 mA
Voltage input signal	0 V 10 V, -10 V 10 V
Max. permissible current	± 100 mA (Current inputs)
A/D conversion time	typ. 120 µs (per channel)
Measured value representation	13 bits (12 bits + sign bit)
Data formats	IB IL, IB ST, IB RT, standardized representation
Averaging	Over 16 measured values (can be switched off)
Process data update	< 1.5 ms (The time includes the internal firmware runtime and the time for the analog-to-digital conversion. For system considerations (e.g., for the step response determination of sensors), please take into account additional times for latching and bus transmission as well as the status of mean-value generation.)
Input resistance of voltage input	> 220 kΩ
Input resistance current input	50 Ω (Shunt)
Limit frequency (3 dB)	40 Hz
Open circuit response	Countering 0 V, 0 mA or 4 mA, an open circuit message is issued in the process data from <3.2 mA in the measuring range of 4 mA 20 mA
Permissible voltage	max. ± 32 V (between analog voltage inputs and analog reference potential) max. ± 5 V (between analog current inputs and analog reference potential, correspond to 100 mA through the shunts)
Common mode voltage range	40 V (between current input and functional earth ground) 40 V (between voltage input and functional ground)
Common mode rejection (CMR)	min. 90 dB (Current and voltage input signal, valid for approved DC common-mode voltage range) typ. 110 dB (Current and voltage input signal, valid for approved DC common-mode voltage range)
Surge protection	Suppressor diodes in the analog inputs
Programming data (INTERBUS, local bus)	
ID code (hex)	7F
ID code (dec.)	127
Length code (hex)	02
Length code (dec.)	02
Process data channel	32 Bit
Input address area	4 Byte
Output address area	4 Byte

7037\_en\_02 PHOENIX CONTACT 5 / 19

#### Programming data (INTERBUS, local bus)

Parameter channel (PCP) 0 Byte Register length (bus) 32 Bit



For the programming data/configuration data of other bus systems, please refer to the corresponding electronic device data sheet (e.g., GSD, EDS).

#### Configuration and parameter data in a PROFIBUS system

Required parameter data 6 Byte
Required configuration data 4 Byte

#### Error messages to the higher level control or computer system

Failure of the internal I/O supply

Yes

Peripheral fault Error message in the process data
User error Error message in the process data

## Electrical isolation/isolation of the voltage areas

Lieutical isolation/isolation of the voltage areas	
Test section	Test voltage
7.5 V supply (bus logic), 24 V supply U <sub>ANA</sub> / I/O	500 V AC, 50 Hz, 1 min.
$7.5V\text{supply}$ (bus logic), $24V\text{supply}U_{ANA}/\text{functional}$ earth ground	500 V AC, 50 Hz, 1 min.
I/O / functional earth ground	500 V AC, 50 Hz, 1 min.

#### **Approvals**

For the latest approvals, please visit phoenixcontact.net/products.

#### 5 Additional technical data

The following data deviates from the specifications in the user manual IL SYS INST UM.

Mach	anica	il taete

Shock in acc. with EN 60068-2-27/IEC 60068-2-27 15g load for 11 ms, half sinusoidal wave, three shocks per

space direction and orientation

25g load for 6 ms, half sinusoidal wave, three shocks per

space direction and orientation

#### Immunity test in accordance with EN 61000-6-2

Electrostatic discharge (ESD) EN 61000-4-2 / IEC 61000-4-2

Criterion B; 6 kV contact discharge; 6 kV air discharge

7037\_en\_02 PHOENIX CONTACT 6 / 19

#### 6 Tolerance data

## 6.1 Tolerance and temperature response of the voltage inputs

The tolerance indications relate to the measuring range final value of 10 V.

	Typical	Maximum
Total tolerance of the voltage inputs at 23°C (tolerance through offset, gain, and linearity)	±0.25%	±0.50 %
Total tolerance of the voltage inputs (-25°C +55°C) (tolerance through offset, gain, linearity, and drift)	±0.40 %	±0.75 %

## 6.2 Tolerance and temperature response of the current inputs

The tolerance indications relate to the measuring range final value of 20 mA.

	Typical	Maximum
Total tolerance of the current inputs at 23°C (tolerance through offset, gain, and linearity)	±0.30%	±0.55 %
Total tolerance of the current inputs (-25°C +55°C) (tolerance through offset, gain, linearity, and drift)	±0.45 %	±0.80 %

#### 6.3 Additional tolerances influenced by electromagnetic interference

Type of electromagnetic interference		Typical deviation from the measuring range final value (voltage input)		Typical deviation of the measuring range final value (current input)	
		Relative	Absolute	Relative	Absolute
Electromagnetic fields	EN 61000-4-3/ IEC 61000-4-3	< ±2.0 %	< ±200 mV	< ±2.0 %	< ±400 μA
Fast transients (burst)	EN 61000-4-4/ IEC 61000-4-4	< ±1.0 %	< ±100 mV	< ±1.0 %	< ±100 μA
Conducted interference	EN 61000-4-6/ IEC 61000-4-6	<±1.0 %	< ±100 mV	< ±1.0 %	< ±100 μA

7037\_en\_02 PHOENIX CONTACT 7/19

## 7 Internal circuit diagram

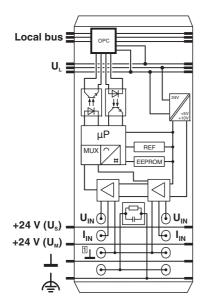


Figure 1 Internal wiring of the terminal points

Key:



Protocol chip



Optocoupler



Power supply unit with electrical isolation



Microprocessor with multiplexer and analog-to-digital converter



Reference voltage source



Electrically erasable programmable read-only memory



Input amplifier



Coupling network



Please refer to the IL SYS INST UM E user manual for an explanation of other symbols used.

#### 8 Electrical isolation

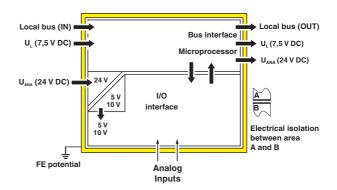


Figure 2 Electrical isolation of the individual function areas

7037\_en\_02 PHOENIX CONTACT 8/19

## 9 Terminal point assignment

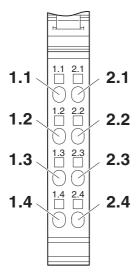


Figure 3 Terminal point assignment

Terminal	Signal	Meaning	
point			
1.1	U1+	Voltage input, channel 1	
2.1	U2+	Voltage input, channel 2	
1.2	l1+	Current input, channel 1	
2.2	12+	Current input, channel 2	
1.3	U1-/I1-	Minus input, channel 1	
		(common for current and voltage)	
2.3	U2-/I2-	Minus input, channel 2	
		(common for current and voltage)	
1.4, 2.4	Shield	Shield connection	

#### 10 Installation instructions

High current flowing through potential jumpers  $U_M$  and  $U_S$  leads to a temperature rise in the potential jumpers and inside the terminal. To keep the current flowing through the potential jumpers of the analog terminals as low as possible, always place the analog terminals after all the other terminals at the end of the main circuit (for the sequence of the Inline terminals: see also IL SYS INST UM E user manual).

#### 11 Connection notes



#### WARNING: invalid measured values

Do not apply current and voltage signals to one input channel simultaneously as you will not obtain valid measured values.



#### **NOTE:** Damage to the electronics

Do not connect voltages above  $\pm 5$  V to a current input. The module electronics will be damaged, as the maximum permissible current of  $\pm 100$  mA will be exceeded.

Always connect the analog sensors using shielded, twisted pair cables.

Connect the shield of the sensor with PE potential.

For cable lengths > 1 m, fold the cable shielding back and connect the shield to the terminal via contacts 1.4 or 2.4. The shield is connected directly to FE on the terminal side via these contacts.

Additional wiring is not necessary.

Supply passive sensors using an external power supply unit or an additional segment terminal with a fuse. See "Connection examples".

7037\_en\_02 PHOENIX CONTACT 9/19

# Within the terminal, the ground is connected to FE via an RC element.

If you want to use **both** channels of the terminal, you have various options to connect the shielding, depending on how the cables are routed.

#### Connection of sensors using a multi-wire bus cable

- Fold the outer sheath of the bus cable back at the required point. Connect the shield to terminal points 1.4 and 2.4 of the Inline connector (A).
- Route the bus cable to the sensors (B).

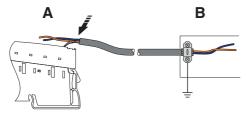


Figure 4 Connection of analog sensors using a multiwire bus cable

#### Connection of sensors via separate cables

To protect against ground loops, close the sensors via separate sensor cables as follows:

- Install a busbar with a connection to the ground potential in front of the Inline terminal (B).
- Fold the outer sheath of both sensor cables back at the required point and connect the shields using a suitable shield clamp.
- Please note that the busbar must be the only point in the wiring at which the shield is connected with the ground potential.
- Route the sensor cables to the Inline terminal. Connect the shields to terminal points 1.4 and 2.4 of the Inline connector (A).
- Route the sensor cable to the sensor, making sure to maintain cable insulation (C).

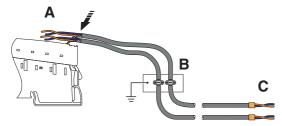


Figure 5 Connection of two analog sensors with separate cables

7037\_en\_02 PHOENIX CONTACT 10 / 19

## 12 Connection examples

#### 12.1 Connection of active sensors

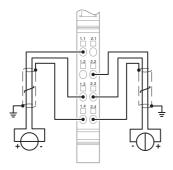


Figure 6 Connection of active sensors in 2-wire technology with shield connection

Left: Active sensor with voltage input (channel 1)
Right: Active sensor with current input (channel 2)

#### 12.2 Connection of passive sensors

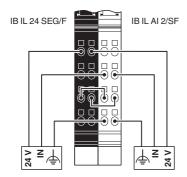


Figure 7 Connection of passive sensors in 2-wire technology with shield connection

The passive sensor supply is indicated in the figure using an upstream segment terminal with fuse.

As an alternative, you can supply the sensors via an external power supply unit.

#### 12.3 Connecting a battery monitor



#### **NOTE: Short-circuit**

Both reference inputs (minus inputs) of each terminal are connected to each other. If signal sources are connected in series, incorrect connections can lead to a short circuit of individual signal sources.

 Observe the following connection example for series connection.

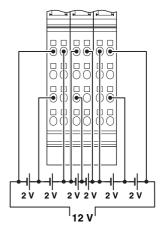


Figure 8 Typical connection for battery monitoring

Because of the single-ended inputs, wire the series connection as follows:

Connect the reference input of one terminal between two voltage sources.

Channel 1 measures the first voltage source with opposite polarity. Adjust the polarity of the measured value in the controller.

Channel 2 measures the second voltage source with correct polarity.

Parameterize the terminal to bipolar  $(\pm 10 \text{ V})$ .

7037\_en\_02 PHOENIX CONTACT 11 / 19

# 13 Local diagnostic and status indicators



Figure 9 Local diagnostic and status indicators

Designation	Color	Meaning
D		Diagnostics (bus and logic voltage)



For detailed information on diagnostics, please refer to the IL SYS INST UM E user manual.

#### **Function identification**

Green

7037\_en\_02 PHOENIX CONTACT 12 / 19

#### 14 Process data

The terminal uses two words of IN process data and two words of OUT process data.

Each channel is mapped to a word.

The analog values are transmitted via the input process data.

You can parameterize the terminal channel by channel via the OUT process data.

#### 14.1 OUT process data

You can parameterize each channel independently of the other channels. Parameterize the first channel via the first output word (OUT0), and the second channel via the second output word (OUT1).

The following parameterization options are available:

- Selecting the measuring range according to the input signal
- Switching off mean-value generation (filter)
- Selecting the formats for representing measured values

The parameterization is not saved. Transmit the parameterization in each bus cycle.

After applying voltage (power up) to the Inline station, the message "Measured value invalid" (error code  $8004_{\text{hex}}$ ) appears in the process data input words. After a maximum of one second, the preset parameterization is accepted and the first measured value is available.

If you change the parameterization, the corresponding channel is re-initialized.

The message "Measured value invalid" (error code  $8004_{\rm hex}$ ) appears in the process data output words for maximum 100 ms.

The following values are preset on the terminal:

Measuring range 0 V ... 10 V

Mean-value generation 16-sample mean-value

Format IB IL



You cannot switch the signal inputs via the OUT process data.

Select the current or voltage measurement by applying the measuring signal at the current or voltage input.

In addition, select the corresponding measuring range via the OUT process data.

Order of the process data words:

OUT00	OUT01
Channel 1	Channel 2

Assignment of the parameter words (OUT00 and OUT01)

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Param- eteriza-	0	0	0	0	0		il- er	0	0	For- mat		Measur- ing range			
tion							<b>5</b> 1			111	aı	""	y i	anı	JC.

#### **Bit 15**

Code (	bin)	Parameterization
dec bin		
0	0	Default
1	1	Parameterization

When bit 15 = 0, the preset (default) is active.

In order to parameterize the terminal, set bit 15 to 1.

Bit 9 ... 8

Code		Filter					
dec	bin						
0	00	16-sample mean-value (default)					
1	01	No filter					
2	10	Reserved					
3	11	Reserved					

#### Bit 5 ... 4

Code		Format (data format)						
dec	bin							
0	00	IB IL (default)	12 bits + sign bit					
1	01	IB ST	12 bits + sign bit					
2	10	IB RT	12 bits + sign bit					
3	11	Standardized representation	12 bits + sign bit					

See also Section "Measured value representation in the different formats".

7037\_en\_02 PHOENIX CONTACT 13 / 19

Bit 3 ... 0

Code		Measuring range
dec	bin	
0	0000	0 V 10 V (default)
1	0001	-10 V +10 V
8	1000	0 mA 20 mA
9	1001	-20 mA +20 mA
10	1010	4 mA 20 mA
Other		Reserved



Set all reserved bits to 0.

## 14.2 IN process data

The measured values and diagnostic messages (in the formats IB IL and standardized representation) are transmitted channel-by-channel to the controller via the process data input words IN00 and IN01.

Order of the process data words:

IN00	IN01
Channel 1	Channel 2

7037\_en\_02 PHOENIX CONTACT 14 / 19

## 15 Formats for representing measured values



Phoenix Contact recommends format IB IL for all controllers as this format contains the most comprehensive diagnostic codes.

The other formats are only intended for simplifying reconfiguration on IB IL analog modules in existing projects.

#### 15.1 IB IL format

The measured value is represented in bits 14 to 3.

An additional bit (bit 15) is available as a sign bit.

This format supports extended diagnostics. Values  $> 8000_{hex}$  and  $< 8100_{hex}$  indicate an error.

The error codes are specified in the section "Supported IB IL error codes and standardized representation".

#### Measured value representation in IB IL format

	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Ī	V		Analog value									Χ	Χ	Χ		

V Sign bit

X Not relevant

#### Significant measured values

Some codes are used for diagnostic functions. In this case, take the full 16-bit value into consideration.

Input data		0 V 10 V	± 10 V	0 mA 20 mA	± 20 mA	4 mA 20 mA
hex	dec	V	V	mA	mA	mA
8001	Overrange	>+10.837	>+10.837	>+21.6746	>+21.6746	> +21.3397
7F00	32512	+10.837	+10.837	+21.6746	+21.6746	+21.3397
7530	30000	+10.0	+10.0	+20.0	+20.0	+20.0
0008	8	+2.667 mV	+2.667 mV	+5.33 μΑ	+5.33 μΑ	+4.004267
0000	0	≤ 0	0	≤ 0	0	+4.0 +3.2
FFF8	-8		-2.667 mV		-5.33 μΑ	
8AD0	-30000		-10.0		-20.0	
8100	-32512		-10.837		-21.6746	
8080	Underrange		< -10.837		< -21.6746	
8002	Open circuit					< +3.2

**7037\_en\_02** PHOENIX CONTACT 15 / 19

#### 15.2 IB ST format

The measured value is represented in bits 14 to 3.

An additional bit (bit 15) is available as a sign bit.

Bits 2 to 0 are measuring range and error bits.

IB ST format corresponds to the data format used on INTERBUS ST modules.

#### Measured value representation in IB ST format

	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
ſ	V		Analog value								0/4	ОС	ΒÜ			

V Sign bit

OC Open circuit

BÜ Overrange

0/4 4 mA ... 20 mA measuring range

#### Significant measured values

Input data		0 V 10 V	± 10 V	0 mA 20 mA	± 20 mA
hex	nex dec		V	mA	mA
7FF9	Overrange	>+10.75	> +10.75	> +21.5	> +21.5
7FF8	32760	+10.0 10.75	+10.0 10.75	+20.0 +21.5	+20.0 +21.5
7FF8	32760	+9.9975	+9.9975	+19.9951	+19.9951
4000	16384	+5.0	+5.0	+10.0	+10.0
0008	8	+0.002441	+0.002441	+0.0048828	+0.0048828
0000	0	≤ 0	0	≤ 0	0
FFF8	-8		-0.002441		-0.0048828
8000	-32768	7	-10.010.75		-20.021.5
8001	-32767		> -10.75		< -21.5
8002	Open circuit				

Input data		4 mA 20 mA
hex	dec	mA
7FFD	Overrange	> +21.5
7FFC	32764	+20.0 +21.5
7FFC	32764	+19.9961
4004	16388	+12.0
000C	12	+4.003906
0004	4	+4.0 +3.2
0006	Open circuit	< +3.2

7037\_en\_02 PHOENIX CONTACT 16 / 19

#### 15.3 IB RT format

The measured value is represented in bits 14 to 3.

An additional bit (bit 15) is available as a sign bit.

 $\ensuremath{\mathsf{IB}}\xspace\,\mathsf{RT}$  format corresponds to the data format used on INTERBUS RT modules.

 $Error \ codes \ and \ error \ bits \ are \ not \ defined \ in \ this \ data \ format. \ The \ positive \ final \ value \ 7FF_{hex} \ indicates \ an \ open \ circuit.$ 

#### Measured value representation in IB RT format

Ī	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	V		Analog value								Х	Χ	Χ			

V Sign bit

X Not relevant

#### Significant measured values

Input data		0 V 10 V	± 10 V 0 mA 20 m/		± 20 mA	4 mA 20 mA
hex	dec	V	V	mA	mA	mA
7FF8	32760	≥ 9.9976	≥ 9.9976	≥ +19.9951	≥ +19.9951	≥ +19.9961
4000	16384	+5.0	+5.0	+10.0	+10.0	+12.0
0008	8	+2.447 mV	+2.442 mV	+4.883 μΑ	+4.883 μΑ	+4.0039
0000	0	≤ 0	0	≤ 0	0	+4.0 +3.2
FFF8	-8		-2.442 mV		-4.883 μΑ	
8008	-32760		-9.99939		-19.999389	
8000	-32768		≤ -10.0		≤ -20.0	
7FF8	32760					< +3.2

7037\_en\_02 PHOENIX CONTACT 17 / 19

#### 15.4 Standardized representation format

The measured value is represented in bits 14 to 3.

An additional bit (bit 15) is available as a sign bit.

In this format, data is standardized to the measuring range and represented in such a way that it indicates the corresponding value without conversion. In this format, one bit has the value of 1 mV or 1  $\mu$ A.

The quantization from bit 3 is therefore 8 mV or 8  $\mu$ A.

This format supports extended diagnostics. Values  $> 8000_{hex}$  and  $< 8100_{hex}$  indicate an error.

The error codes are specified in the section "Supported IB IL error codes and standardized representation".

#### Measured value representation in standardized representation format

	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Ī	V		Analog value									Χ	Χ	Χ		

V Sign bit

X Not relevant

#### Significant measured values



Due to the standardized representation not all of the possible codes are used. In addition, some codes are used for diagnostic functions. Therefore, the resolution is not 15 bits but exactly 13.287713 bits.

Input data		0 V 10 V	± 10 V	0 mA 20 mA	± 20 mA	4 mA 20 mA	
hex	dec	V	V	mA	mA	mA	
8001	Overrange	>+10.837	>+10.837	> +21.6747	> +21.6747	> +21.339	
4E20	20000	-	-	+20.0	+20.0	-	
3E80	16000	-	-	+16.0	+16.0	+20.0	
2710	10000	+10.0	+10.0	+10.0	+10.0	+14.0	
1388	5000	+5.0	+5.0	+5.0	+5.0	+9.0	
0008	8	+0.008	+0.008	+0.008	+0.008	+4.008	
0000	0	≤ 0	0	≤ 0	0	+4.0 +3.2	
FFF8	-8		-0.008		-0.008		
EC78	-5000		-5.0		-5.0		
D8F0	-10000		-10.0		-10.0		
B1E0	-20000				-20.0		
8080	Underrange	7	< -10.837		< -21.675		
8002	Open circuit					< +3.2	

7037\_en\_02 PHOENIX CONTACT 18 / 19

#### 15.5 Supported error codes for IB IL and standardized representation formats

In IB IL and standardized representation formats, a diagnostics code is mapped in the event of an error.

Code (hex)	Cause
8001	Measuring range exceeded (overrange)
8002	Open circuit
8004	Measured value is invalid
8010	Configuration invalid
8020	Sensor and/or analog supply not present
8040	Device faulty
8080	Below measuring range (underrange)

#### 15.6 Example

Measured value representation in different data formats

Measuring range 0 mA ... 20 mA

Measured value 10 mA

Format	Value		Measured value
	hex	dec	
IB IL	3A98	15000	10 mA
IB ST	4000	16384	10 mA
IB RT	4000	16384	10 mA
Standard- ized repre- sentation	2710	10000	10 mA

#### 15.7 Assignment of the terminal points to IN process data

(Word.bit)	Word							W	ord x								
view	Bit	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
(Byte.Bit)	Byte				Byte	0							By	te 1			
view	Bit	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
Channel 1	Signal						minal I										
		Terminal point 1.2: current input															
	Signal reference		Terminal point 1.3														
	Shielding						Te	rmina	al poi	nt 1.4	1						
Channel 2	Signal					Ter	minal <sub>l</sub>	point	2.1:	voltaç	ge in	put					
			Terminal point 2.2: current input														
	Signal reference		Terminal point 2.3														
	Shielding						Te	rmina	al poi	nt 2.4	1						

Word x	Channel
IN00	1
IN01	2